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on

Instrumentation for Continuous Polarimetry

Measurements of Satellite Transmissions

by

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ABSTRACT

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The development of a continuous polarimeter applicable to Faraday rotation investigation of satellite transmissions is presented. The system is designed to overcome ambiguities in determination of the Faraday rotation at the ground, under conditions which are likely to produce fluctuations or changes in the direction of rotation. This is accomplished by resolving the linearly polarized wave into its component oppositely sensed circularly polarized modes using a fixed-geometry antenna system. The component modes are phase compared to determine continuously the position and sense of the plane of polarization of the wave.

I. INTRODUCTION

1. Satellites in Ionospheric Research

The satellite has proved to be an extremely useful tool for the investigation of the upper atmosphere. In the study of the ionosphere, satellites have provided many types of information. For example, a satellite may act as a probe, yielding a wide variety of environmental data; it may act as a sounder by transmitting radio waves downward and measuring the echo range; or the satellite may act as a beacon, transmitting directly to the ground where the radio waves can be analyzed having passed through the ionosphere.

The satellite's primary advantage is its long-term high altitude operation. In this respect, it increases the range of sounding studies to the top half of the electron density profile and overcomes some of the difficulties encountered with the short lifetime of a rocket, which has been the primary vehicle for probe investigation. In addition, a satellite, depending upon its orbit, can provide worldwide coverage thus furnishing data for all types of geographic and geomagnetic conditions.

2. Beacon Satellite Investigations

As a beacon, a satellite transmits linearly polarized waves directly to the ground. Usually these waves are unmodulated and at frequencies somewhat greater than the critical reflection frequency. Ground stations are prepared to analyze the incoming waves for the effects of passage through the ionosphere.

One principal technique involves measurement of the Doppler frequency shift resulting from the satellite's high lateral velocity. At two harmonically related frequencies, the ratio of the observed frequency shifts at the ground usually does not coincide with the ratio of the frequencies, as would be expected in free space. It has been shown that this deviation is dependent upon the integrated electron density along the wave's path.

A second major method of investigation involves observation of Faraday rotation, which can be briefly described as follows. In passage through a medium such as the ionosphere in the presence of a magnetic field, a linearly polarized electromagnetic wave will experience a rotation of its plane of polarization about the axis of propagation. The amount of rotation is dependent upon the total electron content in a narrow column between the satellite and receiver. Instrumentation to measure Faraday rotation is the primary purpose of this investigation.

The satellite's orbit has a pronounced effect on the Faraday rotation observed at a ground station. Steady rotation of uniform direction requires only simple instrumentation; however, several factors may lead to variations in the rotation rate and direction which will be discussed more fully in Chapter II. The most important factor in considering the rotation for a particular orbit is the spatial variation with satellite direction of the earth's magnetic field component longitudinal to the wave normal.

Consequently, a polar satellite is unlikely to produce changes in rotation direction and the Faraday rotation can be

detected by amplitude variations from a linear antenna. However, a satellite with an inclination of 40° passes over a mid-latitude station in a West to East direction and rotation direction changes are common. Therefore, if unambiguous rotation data are to be obtained for an inclined satellite, the instrumentation must be capable of continuously monitoring the angle of the wave's plane of polarization.

A continuous polarimeter could take many forms all a great deal more complex than the linear antenna which detects amplitude nulls every half rotation. To determine the sense of rotation unambiguously, the system must include at least two antennas and related receiving equipment for two channels. Several antennas could be oriented at different angles and the null's progress observed by commutating these, but this system has a resolution limited by the number of antennas.

The best system appears to be one which mechanically follows the rotation; however, the system complexity and size limit its general use. The basic cost and time to construct and maintain such a system make consideration of a simpler system a certainty. Therefore, fixed geometry has been chosen as a system requirement of the polarimeter.

3. Statement of the Problem

A system is to be developed to obtain unambiguous

Faraday rotation data from a satellite pass under conditions which

are likely to produce fluctuations or changes in the direction and

rate of rotation. More explicitly, a fixed-geometry continuous

polarimeter of reasonable simplicity with a resolution on the order

of 5° is required to monitor satellite transmissions for all satellite positions up to about 45° from zenith as viewed from the receiving station. Fixed geometry has been chosen for reasons of size, cost, and maintenance. The resolution of 5° or better has been selected on the basis of the resolution required for a paper chart record at normal chart speeds for satellite data reduction (about 5-15 mm/sec). The 45° angle from zenith corresponds to the normal range of reception for a satellite orbiting at 1000 km with a power output of 100-200 mw and a wave frequency of 20 MHz.

II. THEORY OF FARADAY ROTATION

1. First-Order Theory

In propagating through a magnetoionic medium such as the ionosphere, a linearly polarized plane wave may be considered as the resultant of two oppositely sensed characteristic waves having equal amplitudes but different phase velocities. In general, these waves are elliptically polarized, but may be considered to be circular if the wave frequency is much greater than the plasma frequency. Since the phase velocities of the characteristic modes are unequal, the linearly polarized resultant is seen to rotate about the axis of propagation as the wave traverses the ionosphere. This phenomenon is generally known as Faraday rotation.

It can be shown, in general, that a linearly polarized plane wave is formed by the vector summation of two oppositely sensed circularly polarized waves of equal amplitude. Equations for circularly polarized waves, with left-handed and right-handed senses respectively, may be written as follows,

LEFT HANDED:
$$\overline{E}_{L} = E_{o} \cos \omega t \, \overline{a}_{x} + E_{o} \sin \omega t \, \overline{a}_{y}$$
 (1)

RIGHT HANDED:
$$\overline{E}_{R} = E_{o} \cos (\omega t + \psi) \overline{a}_{x} - E_{o} \sin (\omega t + \psi) \overline{a}_{y}$$
 (2)

where:

 \overline{E}_L , \overline{E}_R = the electric field vector in the plane of polarization for each sense

E = the electric field magnitude of each circularly
polarized component wave

 \overline{a}_{x} , \overline{a}_{y} = unit vectors in the x-, y- direction

 ω = the wave angular frequency

 ψ = the spatial angle between the field vectors for the opposite senses at t = 0.

Let the vector sum of the two modes $(\overline{E}_L + \overline{E}_R)$ be given as \overline{E}_T . Then an expression for \overline{E}_T can be written by vector summation of equations (1) and (2).

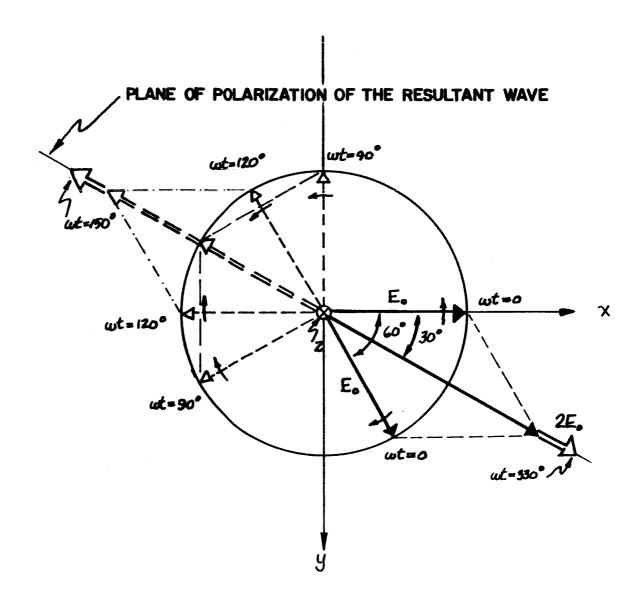
$$\overline{E}_{T} = \overline{E}_{L} + \overline{E}_{R} = E_{o} \left[\cos \omega t + \cos (\omega t + \psi) \right] \overline{a}_{x} +$$

$$E_{o} \left[\sin \omega t - \sin (\omega t + \psi) \right] \overline{a}_{y}$$

$$= 2E_{o} \cos (\omega t + \psi/2) \left[\cos \frac{\psi}{2} \overline{a}_{x} - \sin \frac{\psi}{2} \overline{a}_{y} \right] \qquad (3)$$

Equation (3) can be seen to be the equation of a linearly polarized wave of magnitude $2E_0$ with its plane of polarization oriented at an angle of $\psi/2$ in the right-handed direction from the x-z plane as shown in Figure 1. If the angle ψ should increase steadily while the wave is propagating, it is obvious that the plane of polarization for the linearly polarized resultant wave will appear to rotate. The rate of rotation will proceed at half the rate of change in ψ .

To show that the two modes have different phase velocities, producing variation in ψ , it is necessary to consider their indices of refraction. Assuming negligible attenuation, a wave frequency much greater than the plasma frequency, and for propagation quasilongitudinal to the earth's magnetic field, an expression for the index



LINEAR POLARIZATION AS THE RESULTANT OF TWO OPPOSITELY SENSED CIRCULARLY POLARIZED MODES FOR $\Psi = 60^{\circ}$

FIGURE I

of refraction may be written in the form, [4, 10]

$$\mu^2 = 1 - \frac{X}{1 \pm Y_L} \quad ,$$

which reduces to

$$\mu = 1 - \frac{1}{2} X \pm \frac{1}{2} X Y_{L}$$
 (4)

where,

 μ = the index of refraction

$$X = \frac{(\text{plasma frequency})^2}{(\text{wave frequency})^2} = \frac{f_N^2}{f^2} = \frac{Ne^2}{4\pi^2 \epsilon_0 mf^2}$$

$$Y_{L} = \frac{\text{longitudinal gyro frequency}}{\text{wave frequency}} = \frac{f_{L}}{f} = \frac{B_{o}e \cos \theta}{2\pi mf}$$

 ε_{0} = permittivity of free space

N = electron density

θ = the angle between the wave normal and the earth's magnetic field

B_o = the earth's magnetic flux

m = electron mass

e = electron charge

For a wave frequency of 20 MHz, the ratio f_N is greater than 3:1. This means that the quasi-longitudinal approximation [4,10]

$$\left|\frac{\mathbf{Y}_{\mathbf{T}}^{2}}{2\mathbf{Y}_{\mathbf{L}}}\right| \ll \left|1 - \mathbf{X}\right|$$

is valid with an inequality better than 10:1 for all angles of θ except for the small range of angles 90 ± 2° which, however, cannot be observed in the ionosphere at mid-latitudes.

The Faraday rotation is simply the difference, in radians, between the phase path lengths for the two modes from the satellite to the receiver.

$$\Omega = \frac{\pi}{\lambda} \int_{(+)}^{(+)} \mu_{(+)} ds - \frac{\pi}{\lambda} \int_{(-)}^{(+)} \mu_{(-)} ds$$

$$\begin{array}{ccc} & \text{phase} & \text{phase} \\ & \text{path} & \text{path} \\ & & & & & & \\ & & & & & & \\ \end{array}$$

$$(5)$$

where,

 Ω = the Faraday rotation angle

ds = an element of path length

 λ = the free space wavelength of the wave

 $\mu_{(+)}, \mu_{(-)}$ = the indices of refraction from equation (4)

The two terms in equation (5) may be combined, to a first-order approximation, by performing each integration over the straight line path between the satellite and the receiver.

Since

$$\mu_{(+)} = \mu_{(-)} \approx XY_L$$

Therefore,

$$\Omega = \frac{e^3 \overline{B}_L}{8\pi^3 \varepsilon_0 \text{Cm}^2 f^2} \int \text{Nds}$$
straight line
path

where $\overline{B}_L = \overline{B}_0 \cos \theta$ is the mean value for the component of the earth's magnetic field in the direction of the wave normal, and C is the velocity of light in free space. For a horizontally stratified ionization distribution equation (6) becomes

$$\Omega = \frac{K\overline{M}N_{T}}{f^{2}}$$
 (7)

where,

$$\overline{M} = \overline{B_o \cos \theta \sec \chi}$$

$$K = \frac{e^3}{8\pi^3 \epsilon_0 Cm^2}$$

χ = the angle between zenith and
the straight line ray path

$$N_T = \int_0^h Ndh (h = height)$$

For the case when the ionization is not horizontally stratified, equation (6) can still be written in the form of equation (7), but the quantity N_T must then be interpreted as an "equivalent" vertical column integral. In fact, since the ionization is heavily concentrated about the level of peak density, and lateral variations in N are generally small, this equivalence is found to be physically significant. In this study, it is intended to invoke this interpretation only for purposes of qualitative discussion.

2. Satellite Applications

Equations (6) and (7) describe, to a first-order approximation, the total angle of Faraday rotation experienced by an electromagnetic

wave in propagation from the satellite to the ground. However, the ground observer can only detect changes in rotation. Increases or decreases in the total angle appear as rotation of the wave's plane of polarization at the ground. Consequently, it is the rate of rotation that is measured rather than the total angle. Taking the time derivative of equation (7) produces,

$$\frac{d\Omega}{dt} = \frac{K}{f^2} \overline{M} \frac{dN_T}{dt} + \frac{K}{f^2} N_T \frac{d\overline{M}}{dt}$$

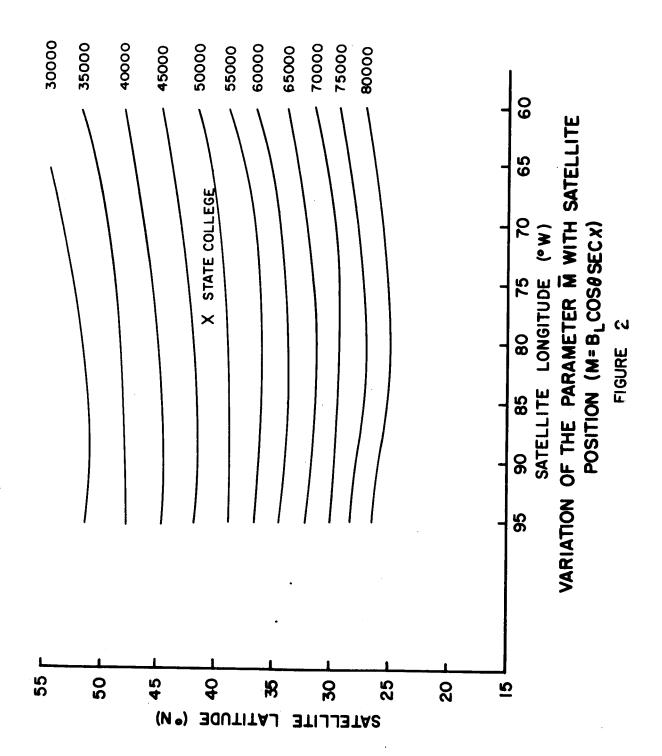
which written in terms of spatial gradients becomes,

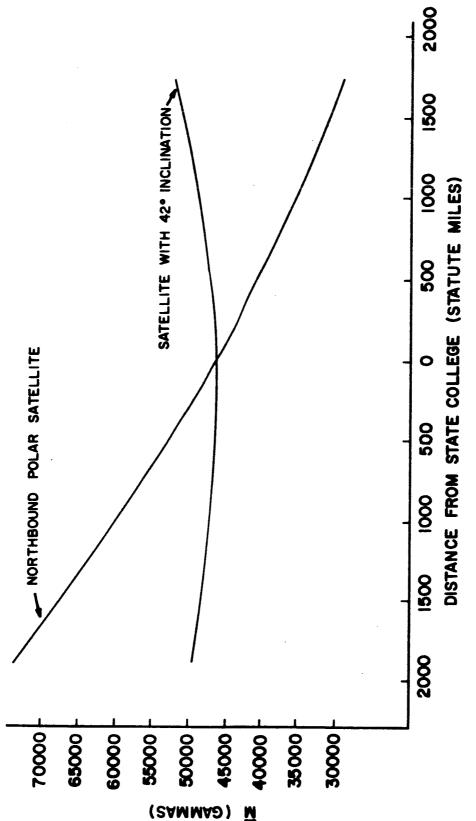
$$\frac{d\Omega}{dt} = \frac{K}{f^2} \overline{M} \frac{\partial N_T}{\partial t} + \frac{K}{f^2} \overline{M} \frac{\partial N_T}{\partial x} \overline{V} + \frac{K}{f^2} N_T \frac{d\overline{M}}{\partial x}$$
(8)

where, \overline{V} = the horizontal component of velocity for the straight line ray path at the mean ionospheric height.

If a horizontally stratified ionosphere is assumed, the second term in equation (8) vanishes. The first term is usually very small since time variation of $N_{\rm T}$ is diurnal. However, if the third term is small, the relative importance of any horizontal or time variations is magnified and the first two terms may not be neglected.

The spatial gradient of \overline{M} is highly dependent upon the satellite orbit. Figure 2 shows the distribution of \overline{M} around State College (40.8 °N, 77.9°W) as a function of satellite position for a satellite height of 1000 km. It is easily seen that a satellite with a near polar orbit will have a large \overline{M} gradient, whereas one inclined 40° from the equator will have a very small gradient (see Figure 3)





VARIATION OF THE PARAMETER W WITH DISTANCE FROM STATE COLLEGE FOR OVERHEAD PASSES OF A POLAR AND 42° INCLINED SATELLITE ORBITING AT 1000 KM.

FIGURE 3

since it passes over State College along a West-East path as demonstrated in Figure 4.

For the satellite with 41° inclination, any one of the three terms in equation (12) could result in a change of sign corresponding to a change in the rotation direction as seen on the ground. For example, the satellite moving into the sunlit hemisphere will encounter gradients in integrated electron density resulting from increased ionization. Further, careful study of Figures 2, 3, and 4 reveals that the \overline{M} gradient will change sign for an inclined satellite.

It may be concluded that a satellite with an inclination of about 41° is very likely to transmit signals which will result in fluctuations or changes in Faraday rotation direction at a mid-latitude ground station. On the other hand, signals from a near polar satellite are unlikely to change rotation direction for such a station, although the possibility does exist and in reality occurs occasionally in the presence of a large gradient of electron content.

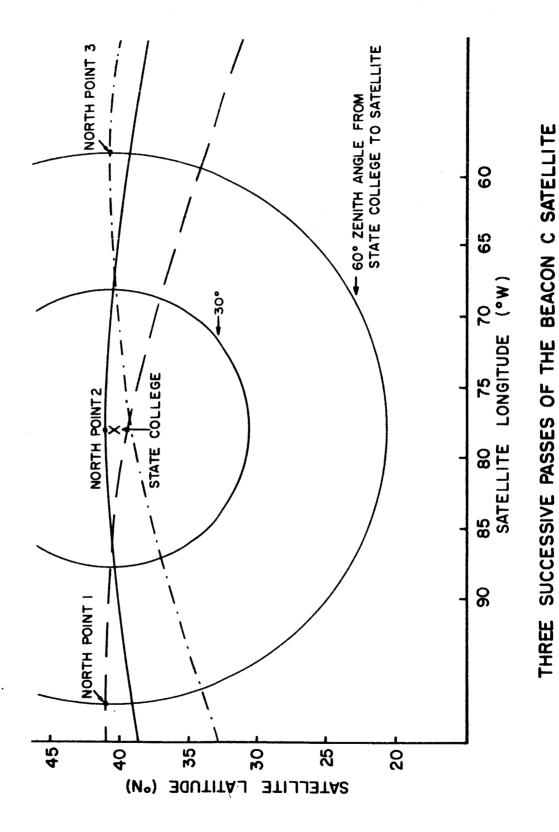


FIGURE 4

III. DEVELOPMENT OF THE INSTRUMENTATION

1. The Satellites

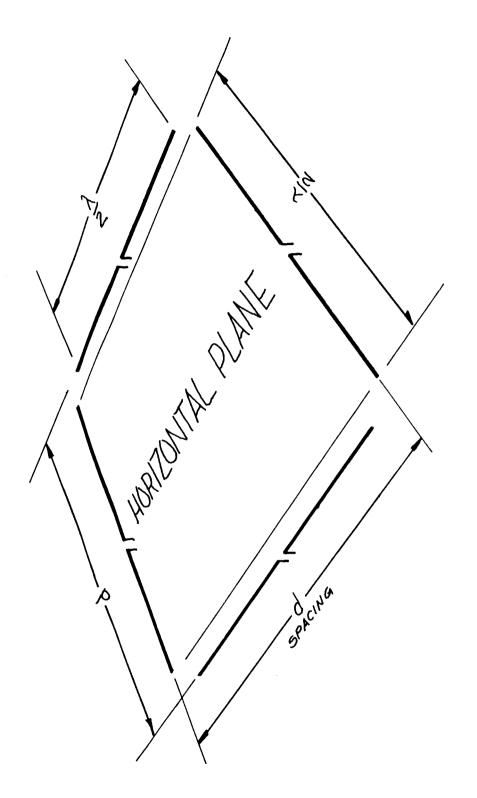
Two ionospheric research beacon satellites have been available for this study, S-66 Beacon B which has a near polar orbit, and S-66 Beacon C which has an inclination of 41°. Both have near circular orbits and a nominal altitude of 1000 km. Typical orbit parameters for the two satellites are as follows:

	Beacon B	Beacon C
Nodal Period (minutes)	104.8	107.7
Inclination (degrees)	79.7	41.2
Perigee Height (kilometers)	890	940
Apogee Height (kilometers)	1070	1320

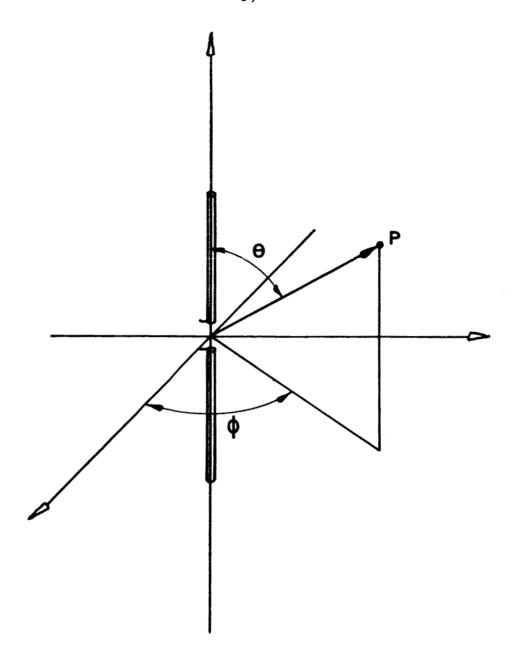
Both satellites transmit continuous unmodulated linearly polarized waves at 20 MHz, 40 MHz, and 41 MHz with power outputs of 250 mw. The satellite antennas are dipoles oriented normal to the axis which is magnetically stabilized; therefore, only one end of the satellite is presented to a mid-latitude receiving station.

2. The Antenna System

Continuous polarimetry can be achieved if the linear polarization of the wave is considered as the phase difference between its two oppositely sensed, circularly polarized components as discussed in Chapter II. Development of a circularly polarized



ANTENNA CONFIGURATION



GEOMETRY FOR THE PATTERN OF A DIPOLE ANTENNA

phasor sum of the fields from each point source. The phase difference, using the array mid-point as reference, is given by $\pm kd/2\cos\alpha$, where $k=2\pi/\lambda$ and α is the angle between the path and the array axis as defined in Figure 7. But $\cos\alpha=\sin\theta\cos\phi$, and the total field is given by the cosine of the mid-point phase difference, therefore the relative field pattern is given by

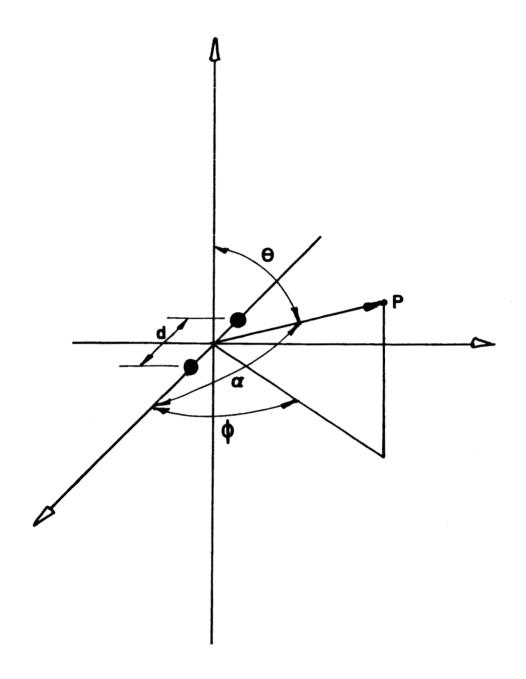
$$E_2 = \cos\left(\frac{kd}{2}\sin\theta\cos\phi\right) . \tag{10}$$

The relative field pattern for two parallel dipoles driven equally, in-phase, and spaced d wavelengths apart is given as the product of equations (9) and (10) following the principle of pattern multiplication.

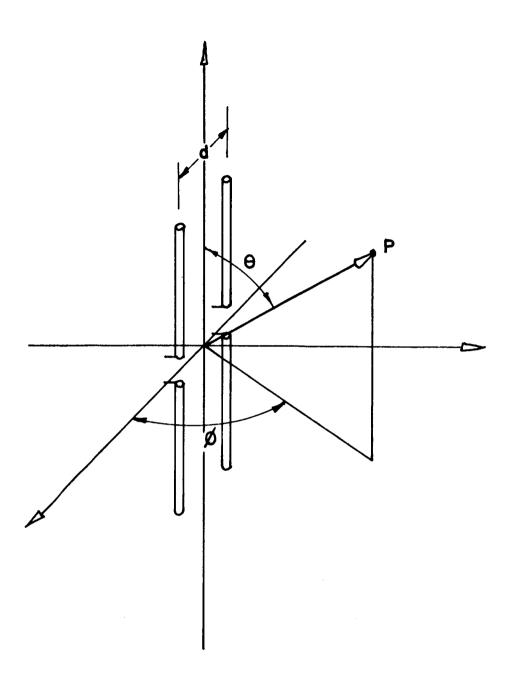
$$E = \frac{\cos(\frac{\pi}{2}\cos\theta)\cos(\frac{kd}{2}\sin\theta\cos\phi)}{\sin\theta}$$
 (11)

The antenna geometry is shown in Figure 8. The broadside pattern, $E(\phi)$, can be obtained from equation (11) by setting $\theta = 90^{\circ}$ in equation (11).

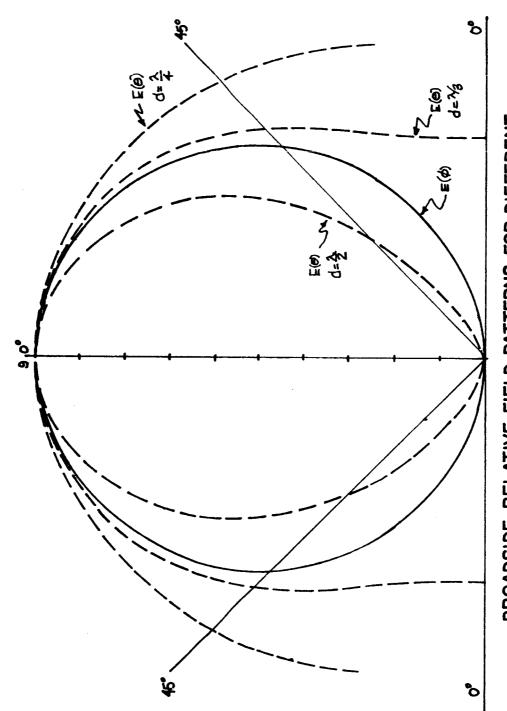
Since, the antennas are separated into opposite pairs, each pair should be omnidirectional to obtain the desired coverage; that is, the end-on pattern of one pair should match the broadside pattern of the other. This sets the criterion for element spacing. It can be seen from Figure 9 that a spacing of 1/3 wavelength produces a very close pattern match up to about 45° from zenith. It should also be noted that the diagonal patterns match through symmetry; therefore, it would appear that the antennas are almost perfectly omnidirectional within the region of interest. This is



GEOMETRY FOR THE PATTERN OF AN ARRAY OF TWO ISOTROPIC POINT SOURCES



GEOMETRY FOR THE PATTERN OF TWO PARALLEL DIPOLES SPACED & WAVELENGTHS



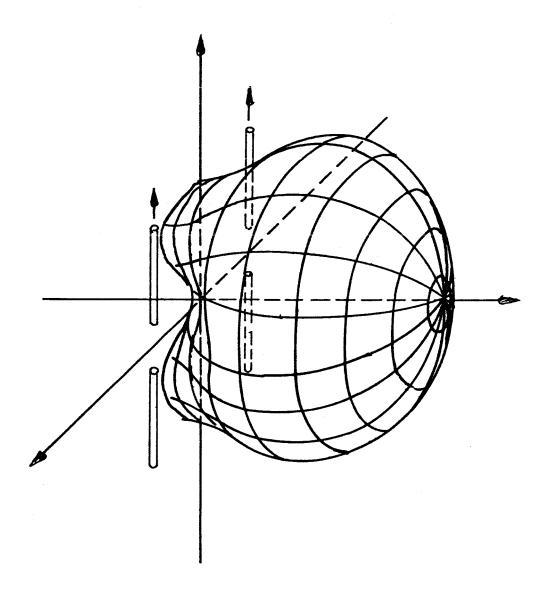
BROADSIDE RELATIVE FIELD PATTERNS FOR DIFFERENT SPACINGS OF TWO PARALLEL DIPOLE ANTENNAS AND THE END.ON PATTERN

shown to be true by equation (11) which is plotted in Figure 10.

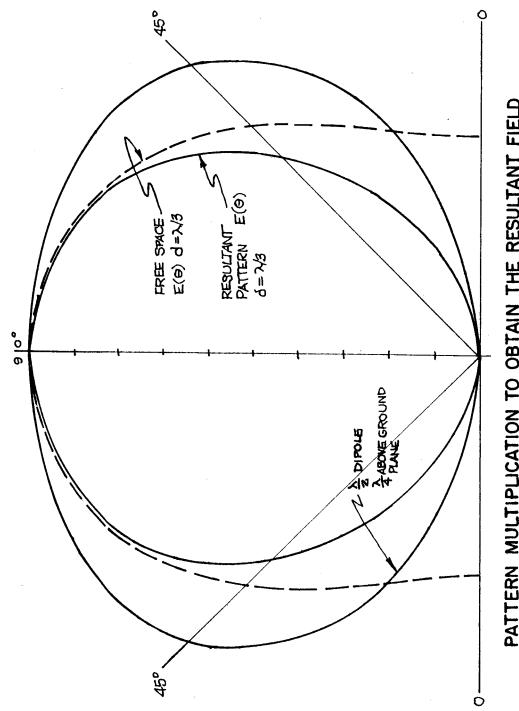
Degradation of the free space field pattern occurs when the antennas are mounted horizontally above a ground plane. For an antenna height of 1/4 wavelength, the broadside pattern of a single dipole nulls at $\phi=0$; whereas, it was independent of ϕ in free space. This pattern is plotted in Figure 11 along with the pattern for two isotropic point sources in free space. The resultant pattern has been obtained by pattern multiplication and is also shown. The resultant end-on pattern appears in Figure 12; comparison with Figure 11 shows that the patterns are still almost identical.

It may be observed that the element lengths, 1/2 wavelength, are greater than the element spacing, 1/3 wavelength. This results in an overlapping at the ends of the opposite pairs. Empirically, it was decided to separate the pairs vertically by 1/16 wavelength. It can be seen that 1/16 wavelength is slightly longer than the distance of overlap. The mean element height was chosen at 1/4 wavelength.

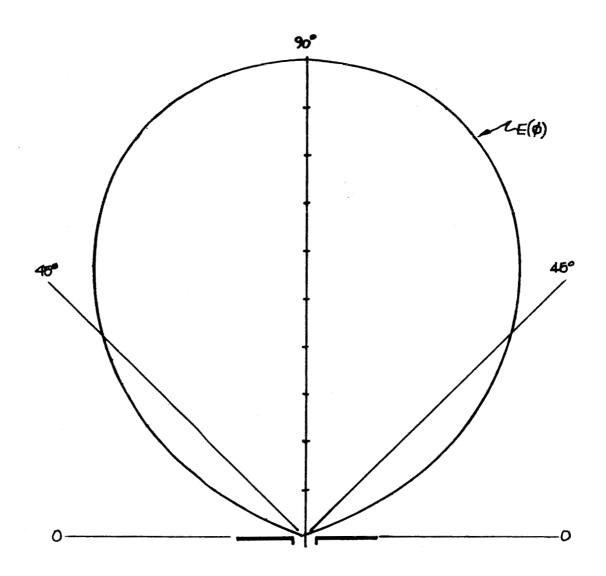
Achievement of circular polarization has been accomplished by connecting opposite elements in phase and phase shifting the perpendicular pairs by 1/4 wavelength. Utilizing the same two pairs and phasing their outputs properly, both senses of circular polarization have been obtained. Each mode then forms a separate channel. Description of the phase shifting system has been deferred to a later section (Section 3.4).



THE THREE DIMENSIONAL FIELD PATTERN OF TWO PARALLEL DIPOLES SPACED $\frac{1}{3}$ WAVELENGTH APART



PATTERN MULTIPLICATION TO OBTAIN THE RESULTANT FIELD PATTERN FOR PARALLEL DIPOLES 1/4 WAVELENGTH ABOVE A PERFECT GROUND PLANE



THE END-ON FIELD PATTERN FOR PARALLEL DIPOLES 1/4 WAVELENGTH ABOVE A PERFECT GROUND PLANE

3. Antenna Matching

The antennas, being folded half-wavelength dipoles made from 300 ohm twin-lead, have balanced terminal impedances of about 300 ohms each, and must be matched to 75 ohm unbalanced coaxial cable. In addition cables of equal length from opposite antennas must be joined and matched to a 75 ohm unbalanced line.

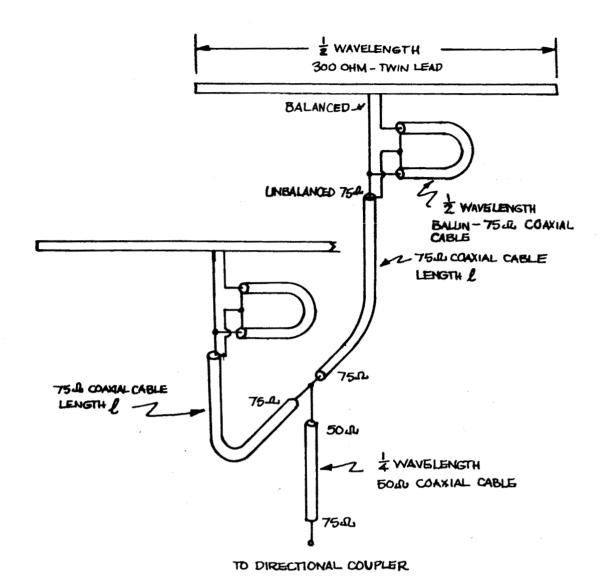
The balanced to unbalanced conversion has been accomplished using half-wave 75 ohm coaxial cable baluns as shown in Figure 13. An impedance match of two joined 75 ohm lines to 75 ohm line has been provided by a quarter-wavelength section of 52 ohm cable. This was derived from the impedance transformation equation for odd multiples of quarter wavelengths,

$$Z_{s} = \frac{Z_{o}^{2}}{Z_{L}}$$

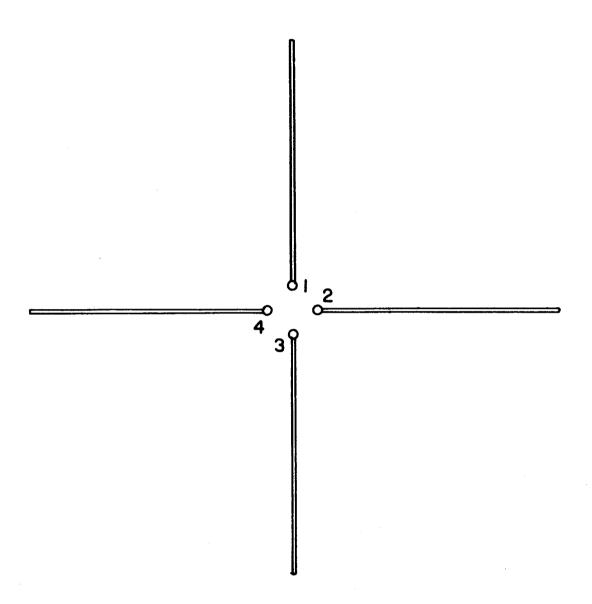
where \mathbf{Z}_{s} and \mathbf{Z}_{L} are the terminal impedances and \mathbf{Z}_{o} is the characteristic line impedance.

4. The Antenna Phasing Network

The phasing system must properly phase and isolate the two pairs of linearly polarized antennas to produce the equivalent of two oppositely sensed circularly polarized antennas. The phasing requirements can be seen more readily by considering a pair of crossed dipoles as illustrated in Figure 14. If terminal 1 is connected directly to the lead-in cable and terminal 2 is connected to the same lead-in cable through a 1/4 wavelength phasing section, the resulting antenna system will be circularly polarized from above



ANTENNA MATCHING



CROSSED DIPOLE ANTENNAS
FIGURE 14

with right-handed sense. Left-handed sense is possible by driving terminal 2 directly and terminal 1 through a 1/4 wavelength phasing section.

Since the antenna system has its opposite elements connected together, its phasing requirements are identical to those for the crossed dipoles. The pairs of elements are oriented North-South (NS) and East-West (EW) respectively, and the right-handed and left-handed polarizations are labelled polarimeter channels A and B respectively.

Consequently, the NS pair must drive the A receiver directly and the B receiver with a 1/4 wavelength lag. Conversely, the EW pair must drive the B receiver directly and the A receiver with a 1/4 wavelength lag. Also, the NS pair must be electrically isolated from the EW pair and receiver A isolated from receiver B.

The phasing could be accomplished through the use of isolation amplifiers and 1/4 wavelength phasing lines; however, a passive configuration exists which will fill the need with only four 1/4 wavelength sections of line. This configuration is usually called a magic-T or hybrid-T. Obtained from waveguide theory, the coaxial line magic-T which is shown in Figure 15 has an extremely complicated derivation which can be found in the microwave literature. [2,9]

The constructed magic-T functioned in the laboratory according to the theory. With all terminals properly loaded and one input, half the power appeared at each output and no measurable signal appeared at the second input. The system operated well

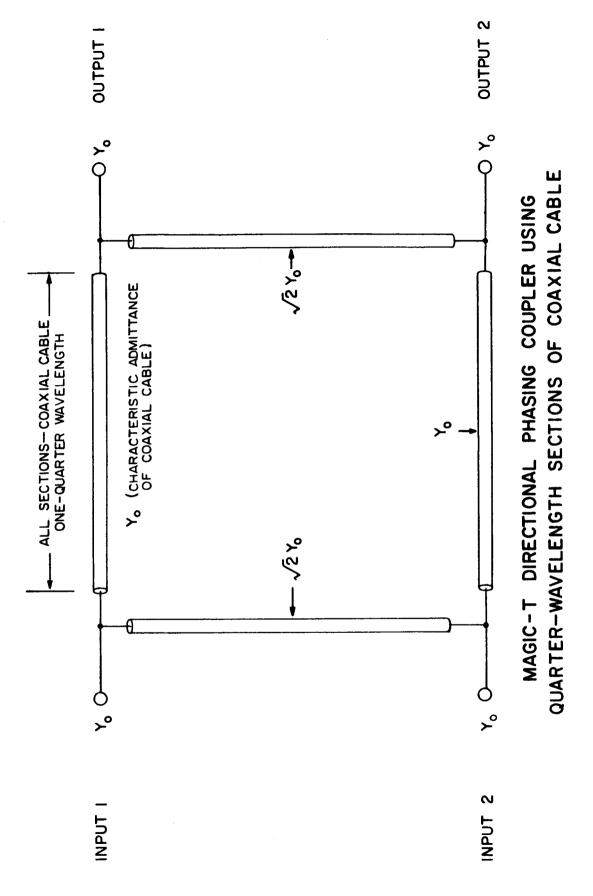


FIGURE 15

within about 20% of the design frequency; outside this range some signal began to appear at the second input. The phase shifting operated as expected with negligible phase shift between the 1 input and the 1 output and 90° phase shift between the 1 input and 2 output. The signal was then applied to input terminal 2 and similar results were obtained as would be expected from the symmetry of the system.

5. The Receiving System

Since the polarimeter operation depends upon phase information between the two circularly polarized channels, the receiving system must be capable of preserving relative phase. Further, it is desirable to have an audio frequency at the receiver output whose amplitude and phase correspond to those at the input. As audio frequency signals, the receiver outputs can be easily handled and recorded on magnetic tape. An additional problem is presented by the Doppler frequency shift resulting from the satellite's motion relative to the receiving station. The receiver bandwidth must be wide enough to accommodate the frequency shift, but it should be as narrow as possible to limit received noise levels and station interference.

Preservation of the phase relationship between the polarimeter channels requires the use of receivers with a common frequency reference. Usually, this is achieved through the use of a stable master oscillator for all of the receivers; however, the Doppler frequency shift requires a tracking oscillator if a constant

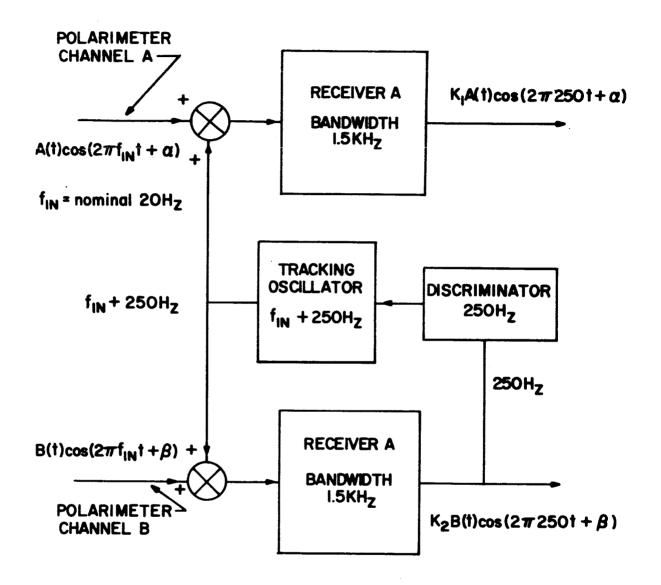
frequency audio output is to be obtained. The Doppler frequency shift for a close pass of a satellite of 1000 km altitude transmitting has a maximum of about 500 Hz from the nominal 20 MHz. This requires about 1 KHz tracking and receiver bandwidth.

The tracking oscillator is a voltage controlled crystal oscillator capable of about 500 Hz deviation from a nominal 1 MHz. The audio output from a receiver for a circularly polarized channel is filtered and used to drive the tracking oscillator. The output of the tracking oscillator contains selected harmonics of a nominal 10 MHz. The first harmonic, which is 250 Hz higher in frequency than the incoming signal at 20 MHz, is then mixed with the antenna signal. Thus the receiver output is at a constant 250 Hz for 20 MHz with amplitude and phase corresponding to the polarimeter signal.

The signals from the receivers are transmitted via telephone line to the recording site. After selective filtering to remove excess noise, the signals are recorded at 3-3/4 i.p.s. on magnetic instrumentation tape. The tapes are played back at the same speed and the signals are again selectively filtered before further analysis. A block diagram of the receiving system is shown in Figure 16.

6. The Comparator and Display System

The output of the polarimeter system is to appear on a chart record simultaneously with a number of other satellite information channels. It is desired to have a readout which displays directly the



THE RECEIVING SYSTEM
FIGURE 16

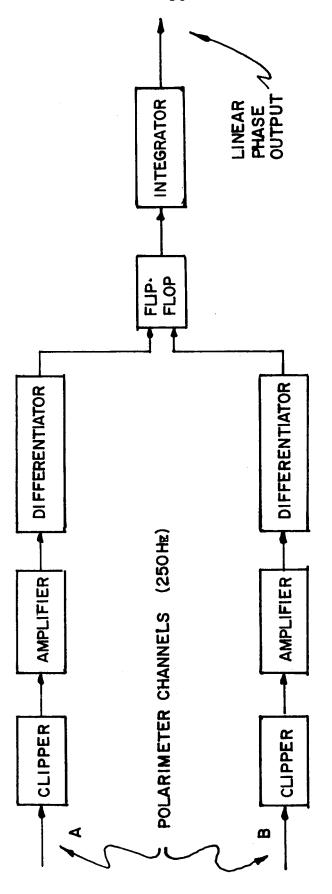
continuous angle of rotation in a manner requiring a minimum of subjective interpretation. In addition, restriction of the output to one chart channel is preferred to allow other information to be simultaneously displayed on the limited number of channels available.

The plane of polarization of the incoming wave can be determined from the phase relationship between the two characteristic modes as discussed in Chapter II. Using one mode as reference, the rotation direction is determined by the direction of the change of phase for the second mode; therefore, a linear phase detector is sufficient since the slope of its output corresponds to the rate of change of phase.

Each 250 Hz signal is clipped at about 10% of its peak value and the resulting almost perfect square wave is amplified and selectively differentiated to provide positive pulses. The time of the pulse corresponds to the leading edge of the square wave which in turn corresponds to the positive going zero crossing of the 250 Hz signal. The two sets of pulses from the differentiators each drive a logic level of a flip-flop. The output of the flip-flop is then a rectangular wave with width corresponding to the phase difference between the 250 Hz signals. This is then integrated with appropriate time constants to produce an output whose slope is proportional to the rate of change of phase. That is, a positive going ramp for clockwise Faraday rotation and a negative going ramp for counterclockwise rotation. This ramp function recycles every 2π radians of phase difference, i.e. every half-rotation of the plane

of polarization.

The time constants were chosen for the integrators using the following criteria. The Faraday rotation period as observed on the ground is seldom less than 3 seconds per rotation. Then 1-1/2 seconds corresponds to the minimum time lapse for the phase between the 250 Hz signals to proceed from zero to 2π radians phase difference. The period for the signal, however, is only .004 seconds. This sets the minimum allowable time constant. The desired 5° angular resolution of the system corresponds to a time .05 seconds which sets the maximum allowable time constant for the integrator. The comparator diagram is shown in Figure 17.



THE PHASE COMPARATOR

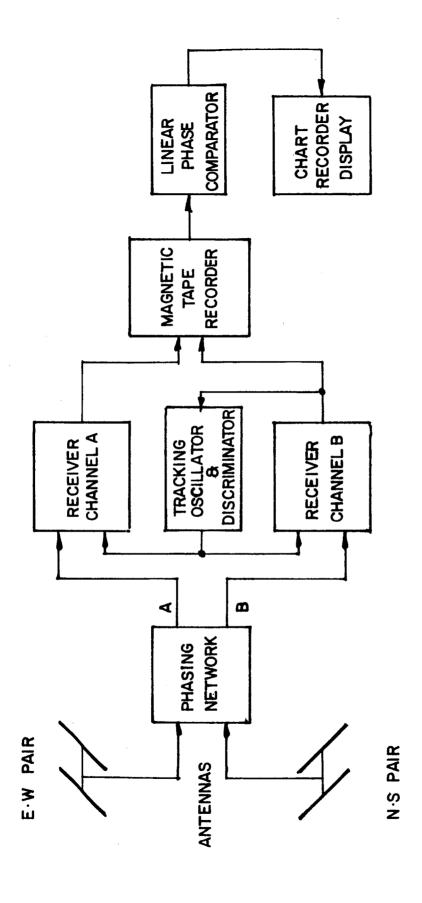
FIGURE 17

IV. THE POLARIMETER OPERATION

A block diagram of the polarimeter system is shown in Figure 18. The accuracy and linearity of the system are determined primarily by the antenna system, its related phasing equipment, and the phase comparator system. Any phase differential between the channels resulting from components other than those listed above will be constant. Consequently, it will not affect the rate of change of phase, but simply shift the zero point at the output. Amplitude inequalities between channels do not noticeably affect the system since the only measurement is of phase, not amplitude. This is not to say, however, that amplitude fluctuations with rotation are tolerable, since these correspond to ellipticity in the antenna system.

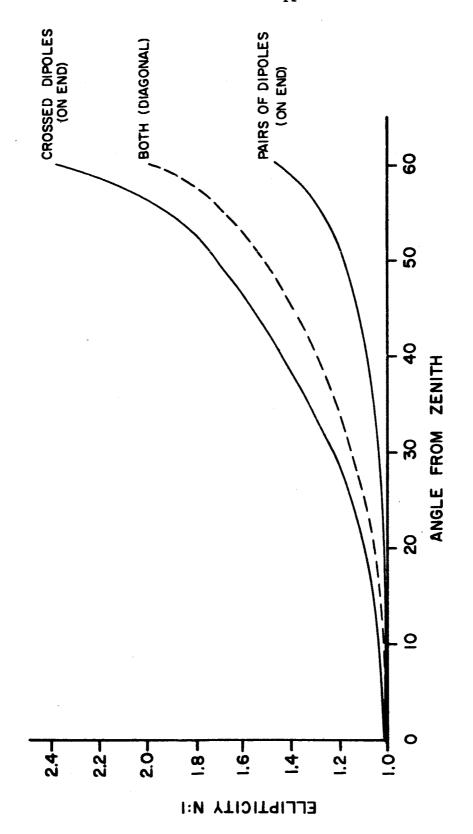
The antenna is the source of greatest error. Limited by fixed geometry, the development of an antenna that appears circularly polarized from all directions is an extremely difficult task, consequently ellipticity usually exists and, in this case, is more noticeable at larger angles from zenith. Also, the antenna system appears more elliptical as viewed from the diagonal than when viewed end-on or broadside. The axial ratio has been calculated and plotted in Figure 19 for various angles from zenith. A plot is also shown for simple crossed dipoles to show the improvement in using the four dipole arrangement.

A circulary polarized wave approaching at an angle $\chi=45^{\circ}$ on the antenna diagonal will appear elliptically polarized with an axial ratio of 1.4:1. In this case, which is considered as the worst



THE POLARIMETER BLOCK DIAGRAM

FIGURE 18

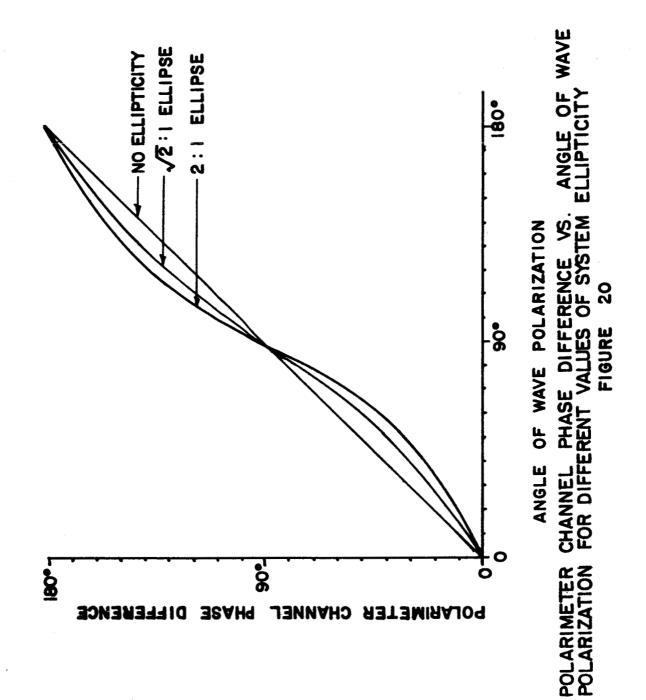


ELLIPTICITY OF THE ANTENNA SYSTEM FOR POSITION AND ZENITH ANGLE OF THE SATELLITE COMPARED TO CROSSED DIPOLES

case, the maximum absolute scale error is 10° occurring when the wave polarization is 45° from vertical. The maximum differential error is 1.4°/degree occurring for vertical wave polarization and 0.7°/degree for horizontal polarization. This means that the remainder of the system must have no worse than 3.5° phase change resolution if 5° overall is required for the system. A plot of the polarimeter channel phase difference versus incoming signal polarization angle is shown in Figure 20 for different degrees of ellipticity.

It should be remembered, moreover, that development of this system follows the need for a continuous polarimeter created by the Beacon-C satellite. By the nature of the satellite's orbit, signals from Beacon-C usually approach the antenna diagonal with small zenith angles. Since antenna ellipticity diminishes near zenith, the characteristic modes of the signal from Beacon-C will usually appear nearly circularly polarized for the entire pass. A plot of the axial ratio of the ellipticity versus satellite position is shown in Figure 21.

The related matching and phasing networks associated with the antennas form a major possibility for error. Any phase differential introduced in the system between the antennas and the phasing network will lead to ellipticity in the system, beyond the phasing network it will result in a scale shift at the output. Consequently, extreme care has been taken to ensure that the cables from all antennas are of equal length and that the related matching networks are as nearly identical as possible. The magic-T phasing



Ŗ	(N°)			r⊔J∃TA8 ₩		
55-	50-	45-	40 -	35-	98	
50	<u>;</u> +	4 +	<u></u>	7 +	<u>;</u> +	- %
<u>r:</u> +	4 +	2. +	=+	7+	4+	-8
ű+	+ :5	=+	0 <u>.</u> +	3 +	<u>7</u> +	l 85 SATE
=+	3 +	6+ 5-	<u>3</u> +	<u></u> 9+	<u>-</u> +	I I 35 80 SATELLITE L
5 +	<u>-</u> +	LO + +	COLLEGE 1.0 © 1.0 + +	2+	5+	1 75 -ONGITUDE
<u></u> +	7.+	<u>=</u> +	<u>.</u> +	::+	<u>:</u> +	70 70 F (•W)
<u>r</u> +	<u>4</u> +	2+	<u>-</u> +	2+	<u>+</u> +	- 8
+0	<u>r</u> +	<u>4</u> .+	+:2	4 +	<u>r</u> +	- 9

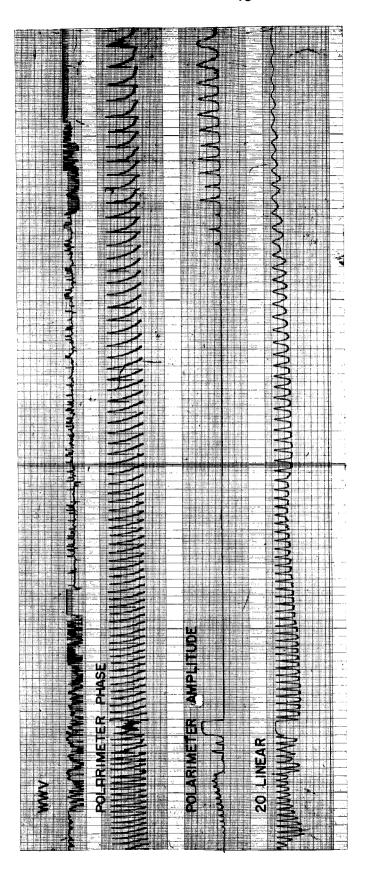
AXIAL RATIO OF ANTENNA ELLIPTICITY VS. SATELLITE POSITION

network has been laboratory tested and found to be balanced. It, therefore, has been assumed that no appreciable errors exist resulting from the phasing and matching networks.

Polarimeter amplitude records shown in Figures 22 through 26 give some indication as to the circularity of the antenna system. It can be seen that slight amplitude variations resulting from rotation of the plane of polarization appear early and late in the pass. The existence of variation indicates ellipticity in the system with an axial ratio corresponding to the degree of variation. During most of the pass, however, the amplitude does not vary significantly indicating antenna circularity.

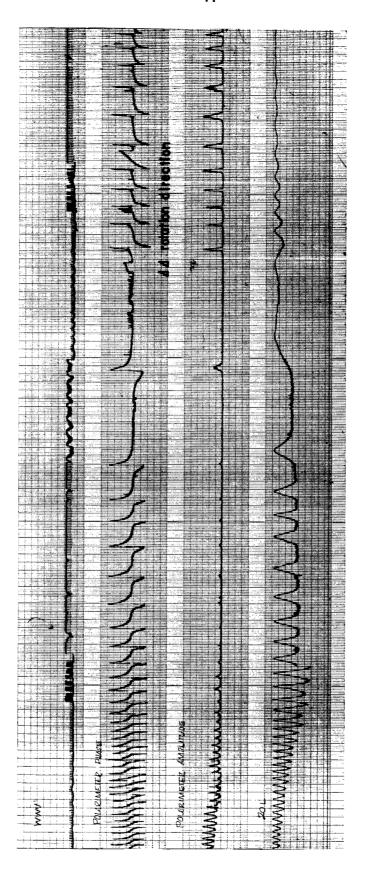
The only other major source of error is the phase comparator system. Tested in the laboratory where the phase of two input signals could be controlled, it was found to be quite linear over most of its range of operation. However, phase scintillations produced by the wave's passage through the ionosphere cause slight distortion of the output as the phase difference between the polarimeter channels approaches 360°. At this point the phase comparator is faced with a decision whether to display maximum or minimum output since this is the reset value of phase. Further complicated by phase scintillation, the comparator displays a slightly ambiguous output until the fluctuations no longer pass through zero phase. This type of distortion appears more predominately when the rotation is very slow, and usually results in only a few degrees of ambiguity near the reset position.

Typical chart records produced by the polarimeter are



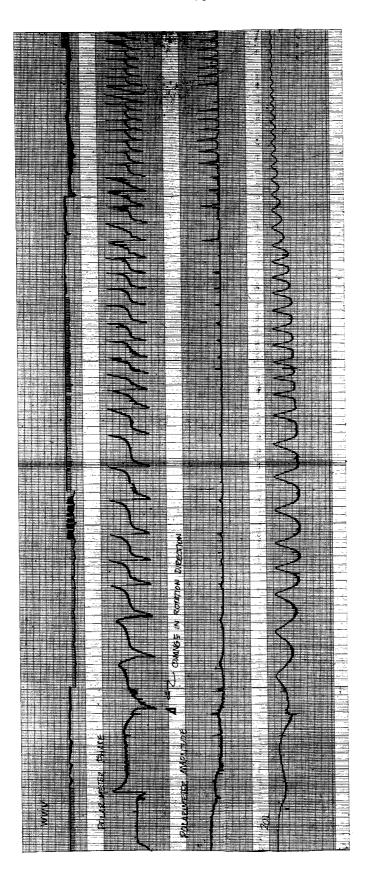
A NORMAL PASS OF BEACON B SATELLITE

FIGURE 22

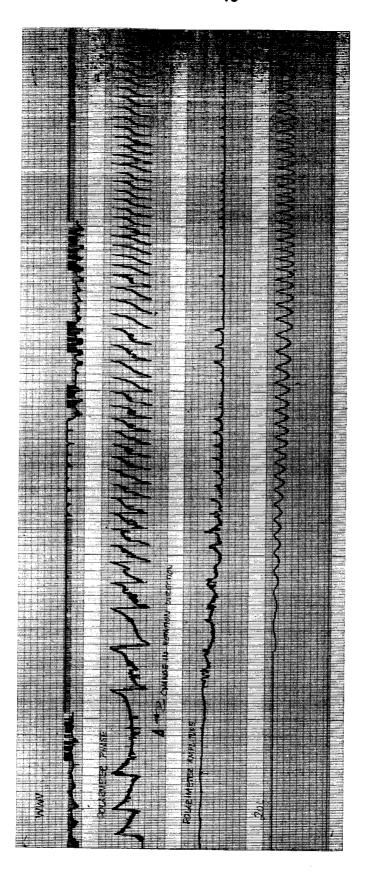


A TYPICAL PASS OF BEACON C SATELLITE

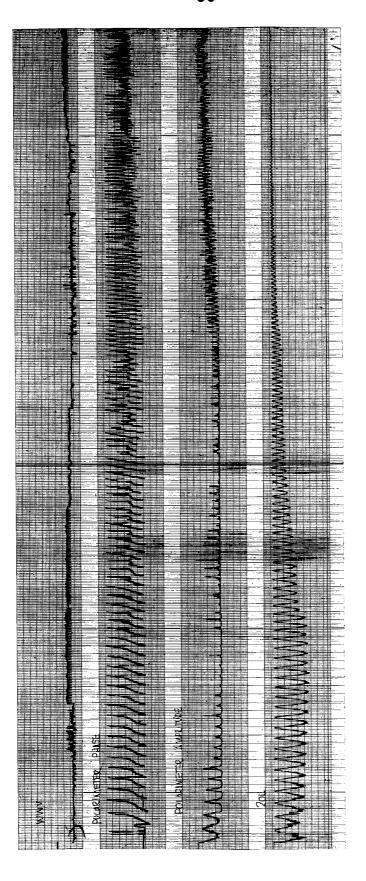
FIGURE 23



A PASS OF BEACON C REVEALING SLIGHT PHASE SCINTILLATION



A PASS OF BEACON C WITH PHASE SCINTILLATIONS



A PASS OF BEACON B WITH PHASE SCINTILLATION

shown in Figures 22 through 26. Figure 22 shows a normal pass of Beacon-B satellite. It can be seen that all of the ramps on the polarimeter display channel slope in the same direction; this corresponds to constant rotation direction. Figure 23 displays a typical record for a daytime pass of Beacon-C. Notice that the ramp display changes its direction of slope at the point indicated by an arrow. A pass of Beacon-C in which there was some signal scintillation appears in Figure 24, and a pass with considerable scintillation is displayed by Figure 25. In both cases, the polarimeter shows the general trend of the rotation and it is possible to count the number of half rotations unambiguously in a given direction. Figure 26 is the record of a nighttime pass of Beacon-B showing scintillation. Even though the rotation does not change direction in Figure 26, valuable information about scintillation and the uniformity of the rotation is obtained.

Figures 22 through 26 also display the modulation from the standard time station WWV for time reference, the amplitude output of a linear E-W antenna for 20 MHz, and the amplitude from one of the polarimeter channels. The amplitude record from the 20 MHz linear antenna shows a null every half rotation, which corresponds to the plane of polarization of the wave being oriented in a North-South direction. This channel serves, in this case, to set the zero point for the polarimeter. It can be seen that for uniform rotation, this channel alone could serve to provide the necessary information for Faraday rotation study.

V. SUMMARY

l. Conclusions

Evolving from a need for more complete knowledge of the Faraday rotation of a linearly polarized satellite transmission, a continuous polarimeter has been developed and constructed. Essentially, the polarimeter independently receives the two oppositely sensed circularly polarized component modes of the 20 MHz linearly polarized wave. It then performs phase measurements between the component modes to determine unambiguously the rate and direction of the polarization rotation. This has been accomplished using a fixed geometry of four half-wavelength dipole antennas. Both senses of circular polarization are received by the same antennas and separated using a directional coupling and phasing network. The component modes are compared using a linear phase comparator such that the slope of the output reveals the rate and direction of the Faraday rotation.

The system is capable of measurements for all sources up to 45° from zenith and is at least capable of detecting all 5° or greater changes in rotation and of absolute angle within 10°. The display output shows continuously the rotation direction and rate as the slope of a linear phase plot.

The experimental system has been used to interpret records of polarization rotation from a number of satellite passages under varying conditions of aspect and for both quiet and disturbed ionospheric conditions. Its performance is found to be generally as

predicted from a theoretical analysis.

2. Suggestions for Further Investigation

The greatest room for improvement in the existing system is the antenna. A marked decrease in the error for absolute angle determination, from its worst case value of 10° to 5°, could be gained from an antenna system half as elliptical at large zenith angles. This could possibly be accomplished by phase measurements from three radially oriented dipoles or by deviating from horizontal plane orientation of the antenna elements. Such a system has been suggested by Brown (1949)^[3] but it is limited to one sense of polarization.

If a technique could be developed to remove the systematic Faraday rotation from the output, the display would reveal only fluctuations in the plane of polarization. This would enable phase scintillation studies to be performed using the polarimeter system. Preliminary investigation suggests that this could be accomplished using a mechanical resolver with a slow response. Driving the resolver with the phase comparator output and subtracting its output from its input should reveal only fluctuations in the rotation. An electrical analog could produce the same results.

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METEOROLOGICAL DATA REPORT

AEROBEE NASA 4.51 UG (23 May 1966)

BY

GORDON L. DUNAWAY

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METEOROLOGICAL DATA REPORT

AEROBEE NASA 4.51 UG (23 May 1966)

Ву

Gordon L. Dunaway

DR-36

June 1966

DA Task IV650212A127-02

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ABSTRACT

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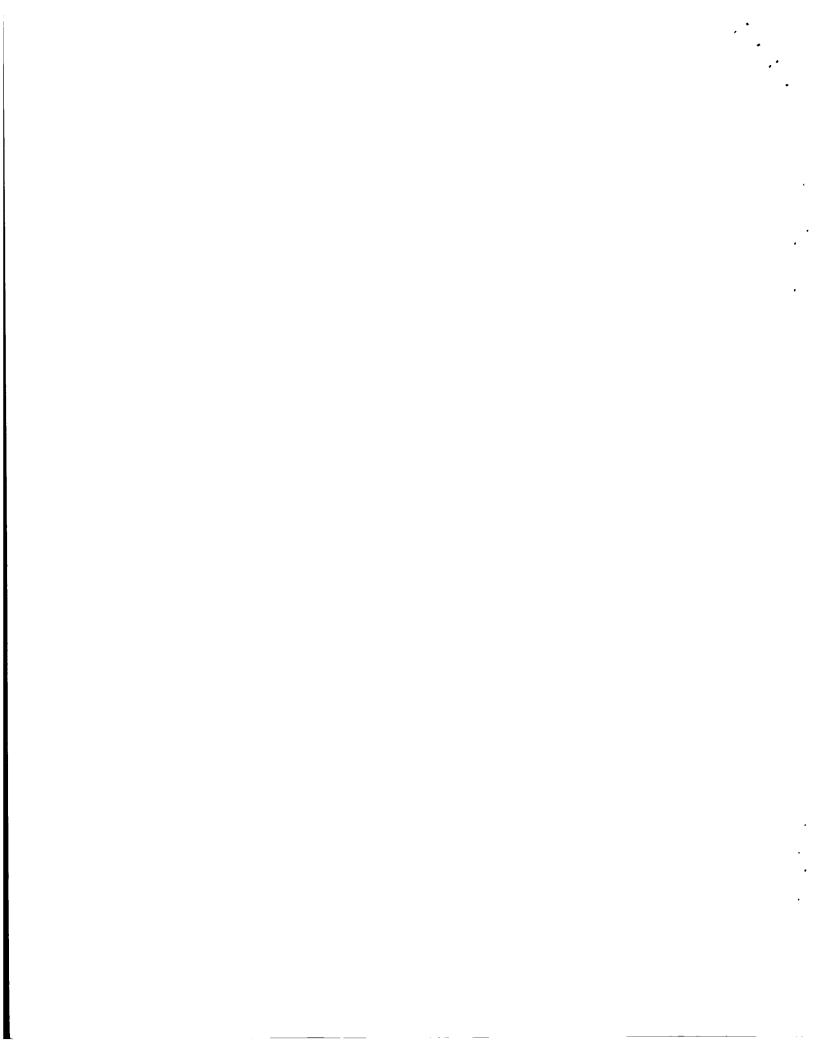
Meteorological data gathered for the launching of Aerobee NASA 4.51 UG are presented for the National Aeronautics and Space Administration, Princeton University and for ballistic studies. The data appear, along with calculated ballistic data, in tabular form.

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INTRODUCTION

Aerobee NASA 4.51 UG was launched by Naval Ordnance Missile Test Facility personnel, White Sands Missile Range (WSMR), New Mexico, at 2207 hours MST, 23 May 1966.

Meteorological data used in conjunction with theoretical calculations to predict rocket impact were collected by the Meteorological Support Division, Atmospheric Sciences Laboratory, White Sands Missile Range, New Mexico. The Ballistic Meteorologists for this firing were Gordon L. Dunaway and Ivan I. Layton.

DISCUSSION

Wind data for the first 4,000 feet above the surface were obtained from a Double-Theodolite Wind Velocity Computer System (1). Balloons released at the launch site were observed and tracked from a 2,000-foot baseline. Continuous angular data were transmitted from two electrically instrumented theodolites to a computer where the data were reduced to obtain a velocity-vs-height relationship. The computer output drives two recorders which trace north-south and east-west components on a specially designed wind velocity computer ballistic chart. It is possible to read directly from the chart both the mean wind component values and the mean ballistic wind components in the various ballistic layers.

Temperature, pressure and humidity data, along with upper wind data from 4,000 to approximately 100,000 feet above the surface, were obtained from standard rawinsonde operations.

Mean wind component values in each ballistic zone were determined from vertical cross sections by equal-area method.

Data appearing in Tables IX, X and XI, are based on the L. D. Duncan (2) theory. The "Predicted Impact" includes, when applicable, an adjustment of impact based on the experience of the Ballistic Meteorologists and the forecast of firing time wind conditions.

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PAYLOAD	Includes Nosecone Weight	300,5	Pounds
	Cross	3.45	Miles/MPH
"UNIT WIND EFFECT	Range	1,06	Miles/MPH
TOWER TILT EFFECT		18,28	Miles/Degree
	Velocity	5,399	Feet/Second
BURNOUT	Altitude	121,100	Feet MSL
	Time	51.8	Seconds
	Altitude	113.0	Miles MSL
PEAK	Time	22h.0	Seconds
TOTAL FLIGHT TIME		525.0	Seconds
CORIOLIS EFFECT	West	5.35	Miles

TABLE I. THEORETICAL ROCKET PERFORMANCE VALUES AEROBEE NASA 4.51 UG

An empirical correction (85 percent of the total) has been made to the cross-unit wind effect. This correction was determined from statistical studies, *

AROVE GROUND	BALLISTIC FACTOR	LAYERS IN FEET ABOVE GROUND	BAILISTIC FACTOR	LAYERS IN FEET ABOVE GROUND	BALLISTIC FACTOR
143- 250	185	3000- 3500	610.	35000- 40000	600.
250- 400	.115	3500- 4000	910.	1,0000- 1,5000	900.
009 -007	,100	1,000- 5000	.031	45000- 50000	.012
008 -009	790.	2000-10000	%0.	20000- 60000	010.
800-1200	.053	10000-15000	950.	00002 -00009	600.
1200-1600	160,	15000-20000	.033	70000- 80000	200.
1600-2000	.025	20000-25000	.023	80000- 90000	.008
2000-2500	.029	25000-30000	,017	000001-00006	010.
2500-3000	.023	30000-35000	ητο·		

TABLE II. BALLISTIC FACTORS
AEROBEE NASA 4.51 UG

MINUTES Speed Knots) Direction (Degrees) T - 15 3.0 356 T - 10 2.0 358 T - 5 1.0 348 T - Time 0.5 330 T + 10 1.0 360 T + 10 1.0 360 T + 15 0.5 358	NT HWE	ANEMOMETER	ANEMOMETER-MEASURED WIND
- 15 3.0 - 10 2.0 - 5 1.0 - Time 0.5 + 5 0.5 + 10 1.0 + 15 0.5	MINUTES	Speed (Knots)	Direction (Degrees)
- 10 2.0 - 5 1.0 - Time 0.5 + 5 0.5 + 10 1.0 + 15 0.5	T - 15	3.0	356
- 5 1.0 - Time 0.5 + 5 0.5 + 10 1.0 + 15 0.5	1	2.0	358
- Time 0.5 + 5 0.5 + 10 1.0 + 15 0.5	EI I	1.0	348
+ 5 0.5 + 10 1.0 + 15 0.5	ı	0.5	330
+ 10 1.0 + 15 0.5	+	0.5	360
0.5		1.0	360
	T + 15	0.5	358

TABLE III. ANEMOMETER-MEASURED WIND SPEED AND DIRECTION AEROBEE NASA 4.51 UG

NOTE: Wind speeds and directions are 5-minute averages centered at indicated times.

$\overline{}$		Τ.		M		10			0		0	ъ		2
	6 MST	F. 1		₩0.4	0.9	8.5	0.6	13.0	14.0	15.0	17.0	17.5	19.0	20.5
	6 2107 MST	Z .	CI N	7. S	11.5	12.5	15.5	11.5	7.5	8.5	7.0	6.5	10.0	8.5
	5 MST	13	M.	MO.9	10.01	11.0	13.0	15.0	15.0	18.0	19.0	21.0	21.0	22.0
HOUR	5 2047 MST	2	Ω ! Z	MO.6	10.01	11.0	13.5	6.5	12.5	13.0	11.5	16.5	0.9	6.0
PER	H. MST	;	H-W	MO.9	8,0	11.0	13.5	15.0	15.5	17.0	16.0	16.5	20.5	18.0
IN MILES	μ 2027 MST		N-S	10.5N	12.5	14.0	12.5	10.5	12,0	11.5	7.5	6.5	11.5	11.5
COMPONENTS	3 MST		E-W	7.0W	8,5	12.0	14.5	16.0	19.0	25.5	27.5	39.5	38.5	39.0
ND COME	7000		N-S	1.5N	7,	4.5	7.5	7.5	7.0	7,0	3.5	7. 2.5	2,0	0.0
MEAN WIND	2 Man	TOL	E-W	MO.9	10.0	13.0	15.0	19.0	19.0	20.0	19.0	24.5	23.0	21.5
	2 TOO T	1721	N-S	5.0N	7.0	7.0	7.5	3.5	0.5	1,0	4.5	6.5	4.5	7.0
	E	TCM	E-W	WO.6	11.0	11.5	19.0	17.0	14.5		19.0	19.0	21.0	21.0
		TAN / MEI	N-S	5.5N	4.5	7,	3,0	بر بر	1.0	3.0	5.0	1.5	5.0	8.0
	LAYERS IN FEET	ABOVE	a constant	1),3- 250	250- 100	009 -007	008 -009	800-1200	0091-0081	1600-2000	2000-2500	2500-3000	3000-3500	3500-1000

TABLE IV. PILOT-BALLOON-MEASURED WIND DATA (DOUBLE-THEODOLITE METHOD)
AEROBEE NASA 4.51 UG

MEAN WIND COMPONENTS IN MILES PER HOUR	8 10 11 21.35 MST 21.57 MST 2208 MST	N-S E-W N-S E-W N-S E-W N-S E-W N-S E-W	6.0N 0.0 6.0N 0.0 3.5N 0.0 1.0N 0.5W	10.5 1.0W 11.0 2.0W 3.5 2.0W 2.0 0.5	7.5 4.0 11.0 4.0 8.5 7.0 9.5 4.0	8.5 9.0 8.0 9.0 10.5 9.5 8.0 8.0	7.0 11.0 6.0 13.0 6.5 11.0 3.0 13.0	5.5 14.0 4.5 15.0 6.0 17.0 3.0 15.0	4.5 15.0 4.0 15.0 2.5 17.0 2.0 15.5	2.5 16.0 3.0 19.0 5.0 19.0 3.0 22.0	4.0 19.0 2.0 23.0 2.55 22.0 4.0S 21.5	13.0 28.5 1.0 24.0 1.0N 23.0 0.5N 24.0	
MEAN W	8 2135 MST					4 <i>.</i>							9.5 31.0
	7 2122 MST	N-S E-W	6.0N 1.0W	11.5 3.0 1	8.5 7.0	7.5 9.0	11.5 10.5	7.0 13.5	6.0 11.5	8.5 12.0	6.5 13.5	22.0	8.5 24.0
EF SCOTA L	FEET ABOVE		143- 250 6	250- 400 11	8 009 -007	2 008 -009	800-1200	1200-1600 7	9 1600-2000	2000-2500 8	2500-3000 6	3000-3500 10.5	3500-4000 8

TABLE IV. PILOT-BALLOON-MEASURED WIND DATA (Cont)
OUUBLE-THEODOLITE METHOD)
AEROBEE NASA 4.51 UG

	···········	i				
MEAN WIND OMPONENTS IN KNOTS	1 MST	E-W	MS . SI	20.5	16.0	18.5
MEAN WIND COMPONENTS IN KNOTS	1 2110 MST	N-S	3.0N	7.58	13.5	15.5
LAYERS IN	FEET ABOVE GROUND		7000- 2000	5000-10000	10000-15000	15000-20000

TABLE V. UPPER AIR DATA (4,000-20,000 FT)
AEROBEE NASA 4.51 UG

NA VERS TN		WE	MEAN WIND COMPONENTS	COMPON	TENTS IN	KNOTS	
N S	1630		1 1630 MST	2* 1905 MST	2* MST	3 2207 MST	3 MST
GROUND N-S	N-S		E-W	N-S	E-W	N-S	E-W
5000 3.05	3,05	70	17.5W	0.0	16.0W	4.03	21.5W
10000 8.0	8.0		21.5	1,03	23.5	6.5	18.0
15000 6.5	6.5		18.0	13.5	22.5	16.0	13.5
20000 10.0	10,0		28.0	5.5	30.5	18.5	22.0
25000 0.0	0.0		0.44	7.5	41.5	15.0	41.5
30000 11.05	11,08	ro	0.49	23.5	0.59	23.0	63.0
35000 15.0	15.0		87.0	15.5	88.0	16.0	89.5
0.0	0,0		98.0	16.5	0,46	16.0	89.5
1,5000 0.0	0,0		68.0	0.0	0.49	10.5N	59.0
50000 8, ON	8,0	Z	16.5	4.53	26.5	9.08	52.0
0.00009	0.0	_	23.0	2.0	11.0	0.0	30.0
70000 5.05	5.0	ഗ	0.9	12.5N	7.0压	0.0	14.0E
80000 15.0N	15.0	Z	2.5E	0.0	15.0	3.0N	16.5
80000- 90000 2.5	2,		15.0	3.5N	18.5	0.0	12.0
90000-100000	3.0		16.5	BALLOON	N BURST	2.5N	13.0

TABLE VI. UPPER AIR DATA (4,000-100,000 FT) AEROBEE NASA 4.51 UG

* Rawin, telecompute data not available.

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII

STATION ALTITUDE 3989.0 FEET MSL 23 MAY 66 1630 HRS MST ASCENSION ND. 371

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•		
-	w	Z
-	w	
n		
Ξ		
7.75		
_		

INDEX OF REFRACTION	1.0002	1,00024	1.0002	1.00024	1.00023	1.00023	1.00023	1.00022	1.00022	1.00022	1.00021	1.00021	1.00021	1.000208	1.00020	1.00020	1,00019	1.00019	1,00019	1.00019	1,00018	1,00018	1.00018	1,00017	1,00017	1.00017	1.00017	1.00016	00016	0015
SPEED KNOTS		•	1,	20	6	40	r,	50	N,	Š	Ŷ	æ	e	19.3	6	6	9	å	8	9	ô	-	•	ļ	۰	٠	-	•	\circ	0
WIND DAT DIRECTION DEGREES(TN)	50°	50.	52.	54.	56.	570	570	57.	58°	58°	57.	56.	56.	-	57.	57.	550	520	49°	470	46.	450	46.	46.	4	47.	470	48°	50	520
SPEED OF SOUND KNOTS	683.1	83°	81.	79°	77.	75°	73.	710	70,	58°	99	64°	62.	661.2	59°	57.	56.	54.	52°	51.	49.	47.	45.	440	42.	41°	39°	37.	636.4	m
DENSITY GM/CUBIC METER	89.	89.	77.	66°	54°	43.	32.	921.5	10.	000	89°	19.	67.	856.3	45.	340	23.	12.	010	90°	80.	70°	60.	49.	39.	28°	18,	08.	97.	687.6
RELATIVE HUMIDITY PERCENT	ů	å	ů	4°	Š	υ°	6.9	7°	7	ဆိ	6	ô	Ţ	22.8	40	Ŋ	2	ထ	င်	-4	3	40	9	۲,	8	ŝ	္ပံ	6		6
ERATURE DEWPOINT CENTIGRADE	•		•		-0.3		-1.7				6.4-			4.9-		-7.3			0.6-			-11.0			-13.5	-14.4		~	-19.6	2
TEMP AIR DEGREES	33.7	e C	å	ö	8	~	Š	S.	Ċ,	ဝံ	0,	2	Ŷ	4	c.		ċ	. 0	ø	•	•	0	0		•	0		ę	0	4.7-
PRESSURE MILLIBARS		74.	58.	440	29°	15,	010	87.	730	600	470	340	210	08.	96°	83	710	58,	46.	340	23.	11°	000	89°	77.	67.	56.	45.	35°	24.
GEOMETRIC ALTITUDE MSL FEET	3989.0	000°	50C°	000	500°	000°	5000	000°	500°	000	500°	000	500°	0000	050C°	10001	1500°	2000.	2500.	3000.	3500°	4000	4500.	5000.	5500.	6000.	6500°	7000°	500.	8000.

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont) STATION ALTITUDE 3989.0 FEET MSL 23 MAY 66 1630 HRS MST ASCENSION NO. 311

INDEX OF REFRACTION	1.000155	.00014	.00014	.00014	.00014	.00013	.00013	.00013	.00013	.00013	.00012	1.000126	.00012	.00012	.00012	.00011	.00011	.00011	• 00011	.00011	.00010	.00010	.00010	.00010	.00010	60000*	60000	60000	•0000
TA SPEED KNOTS		23.4		m.	•		\$	ŝ	\$	-	å	6	ċ	å	ຕໍ	Š	7	ဆံ	<u>.</u>		m.	'n	8	-	'n	•	68.4		2
WIND DA DIRECTION DEGREES(IN)	254.1 256.2	57.	58.	57.	57.	57.	58.	50.	52.	64°	99	68 °	69.	69.	69.	669	69°	70.	69.	68.	68.	67.	65.	63.	61.	60°	58.	56.	56.
SPEED OF SOUND KNOTS	633.5	30.	29.	28°	27.	26°	240	22.	21.	20.	19.	8	16°	15.	13.	11.	10.	08.	.90	05°	03.	02.	00	98°	97.	96°	9	594.7	Q,
DENSITY S GM/CUBIC METER	677.4	56.	45.	3	25.	15.	90	97.	87.	770	67.	ဆိ	49°	41.	32.	24.	16.	08.	000	92.	84.	77.	5	,i	3	ů,	7	8	6
RELATIVE HUMIDITY PERCENT	24.3	ċ	ó	6	6	6			0			18.2				•		19.3	19.5	19.7	19,8	19.5**	14,2**	8.9**	3.6**	** •0-	** °0-	** 0-	** •0-
TEMPERATURE R DEWPOINT EES CENTIGRADE	-25.5	29.		-31.1	-32.1	-33.1	-34.1	-35.1	-36.1	-37.1		-39.2	-40.2			~	•	-45.3	Š		å		-53.3	ф ф		0	•	o	•
TEMP AIR DEGREES	18.6	• •		N		4	Š	۴	ထိ	6	.0	-21.1	· C	3	•	.9	-	œ	0		2.	4.	·ru •	-36.6	2	-38.9		٠ <mark>6</mark>	0
PRESSURE MILLIBARS	514.6	· 4	4	. rV	. 9	• •	~	ထ	0	, .	· ·	. *	S	-	6	-	'n	. 9	ထ	: • 	. 4	7	0	ິຕ	9	6	୍ୟ	9	280.5
GEOMETRIC ALTITUDE MSL FEET		19500.0	0000	0500	1000.	1500.	2000	2500.	3000.	3500	4000	4500	5000	5500	0009	6500.	7000	7500.	8000	8500	9000	9500°	0000	0500	1000	1500	2000	2500.	3000

** AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION.

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont)

GEOMETRIC ALTITUDE MSL FEET	PRESSURE MILLIBARS	TEMF AIR DEGREES	MPERATURE DEWPOINT S CENTIGRADE	RELATIVE HUMIDITY PERCENT	DENSITY S GM/CUBIC METER	SPEED OF SOUND KNOTS	WIND DAT DIRECTION DEGREES(TN)	SPEED KNOTS	INDEX OF REFRACTION
33500.0	274.4	6.04-	Ö	*	411.6	593.4	256.1	74.4	
4000,	က		•	*	03.	92.	57.	ŝ	60000
4500.	° N	•	°	** °0-	96.	91°	59.	ထိ	008
5000.	\$	-43.2	ဝံ	** °0-	88.	.06	61°	4°	800
5500		•	•	** °0-	81.	89°	62.	Ö	900
.0009	٠ د	-44.8	°	** 0-	73.	88.	64°	ŝ	900
6500.	6	-45.6	°	** 0-	.99	87.	64.	ŝ	908
7000.	40	0	•	** °O-	59.	86°	65.	3	.00008
7500.	е Ю	7-47-7	°	** *0	53.	84°	65.	4	.0000
8000.	9	6	•	** • 0-	47.	82.	65.	Ŷ,	.00007
8500.	8	0	o	** °0-	41.	81.	65.	6.	.0000
.0006	9	-	°	** • 0-	35.	.61	999	Š	.00007
39500°	о СС	3	•	** • 0-	30.	77.	999	00.	.00007
.0000	9	•	•	-0° **	24.	75.	66°	9	.00007
0500.	o x	•	•	-C. **	19.	73.	.99	03.	.00007
10001	•		ċ	** 0	13.	71.	•99	ထိ	.00007
1500.	 O	8	ဝံ	** 0-	07.	70°	.99	å	.00006
2000.	185.0	-59.0	0	** °0-	01,	69.	65.	89.2	1.000067
2500.	°	6	°	** °0-	94.	.69	65.	\$	90000
3000.	Ġ.	ô	o	** °O-	87.	69	64°	9	90000°
3500°	å	æ	•	** °0-	79.	70.	65.	œ	90000
•	φ ω	æ	ဝ	** °0-	72.	710	66 °	7.	.00006
۰	۰ پ	•	o	** 0-	.99	70.	6 8°	2	.0000
5000.	60 °	•	ဝိ	++ °0-	60ء	69	• 69	ဗိ	•00002
5500°	0	ċ	ô	** °O-	55.	019	70°	-	.00005
0009	52.	-61.5	°	** °0-	50.	99	71.	•	.0000
0		0	°	** 0-	45.	65°	710	ŝ	•000
0	45.	-63.5	•	** °O-	410	63°	71.	å	.00005
0	141.5	-64.5	°	** 0-	36.	62°	71.	•	.00005
•	38°	•	•	-0-	31,	61.	72.	•	•00000

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont)

STATION ALTITUDE 3989.0 FEET MSL 23 MAY 66 1630 HRS MST ASCENSION NO. 371

INDEX OF REFRACTION	1.000050	1.00004	1.00004	1.00004	1.00004	1.00004	1.00004	1.00004	1.00004	1.00004	1.00003	1.00003	1.0000	1.00003	1.00003	1.00003	1.00003	1.00003	1.00003	1.00003	1.00003	1.00003	1.00003	1.00002	0002	0002	000	002	00	000
SPEED KNOTS	•	4.	5	•	3	•	•	ŝ	-	ċ	ŝ	9.	28.8	ထိ	•	ທໍ	3	2.	6	'n	\$			-		•	16.8		10.8	•
WIND DAT DIRECTION DEGREES(TN)	72.	73.	14.	76.	17.	16.	75.	71.	65.	61.	58.	56.	256.2	56.	58.	60.	61.	62.	62.	90	58.	62.	999	73.	81.	87.	93.	10.	39	10.
SPEED OF SOUND KNOTS	560.6	.09	Ō	.09	9	99	09	60.	62.	62.	61.	.09	559.0	58.	57.	. 09	90	58	57.	56.	55.	55.	54.	55.	58°	58.	58.	59.	62.	64.
DENSITY S GM/CUBIC METER	7	20.	15.	10.	04.	•66	4.	90.	84.	79.	76.	72.	168.7	65.	61.	55.	52.	48.	45.	42.	39.	• 9	33.	6	4.	-	æ	•	110	108.0
RELATIVE HUMIDITY PERCENT	++ •0-	** •0-	** °0-	** •0-	** • 0-	+* •0-	+* •0-	++ *0-	** •0-	** °0-	-0. **	** • 0	++ •0-	** •0-	+* •0-	++ • 0-	** •0-	** •0-	** •0-	-O. **	** • 0-	** °0-	+* *0-	++ 00-	** •0-	** 0-	+* 0-	** •0-	** *0-	** °0-
E RELATIV INT HUMIDIT RADE PERCENT	0-	* •0-	0-	-0-	0-	* •0-	* • 0-	0-	* • 0-	* °0-	-0-	0-		-0-	-0-	•0-	-0-	-0-	-0-	•0-	•0-	°0-	•0-	-0-	-0-	0-	0-	0-	01	* 0-
RATURE RELATIV DEWPOINT HUMIDIT ENTIGRADE PERCENT	0 - 0 6.	* 0- 0 6*9	0-	5.9 00.	.0 0.	5.9 00. *	* • 0-	5.9 00.	4.2 00. *	4.6 00. *	4 00.	6.2 00.	7.0 00.	7.8 00.	8.5 00.	5.2 00.	6.3 00.	7.1 00.	8.0 00.	8.9 0.	9.4 00.	.8 00.	0.2 00.	0- 0- 6-6	0- 0-	7.2 00.	7.3 00.	6.5 00.	4.1 00.	3.2 00. #
TEMPERATURE RELATIV AIR DEWPOINT HUMIDIT EGREES CENTIGRADE PERCENT	4.7 -65.9 00.	1.4 -65.9 00. *	8.1 -65.9 00.	•0 -65.9 00.	1.9 -65.9 00.	18.9 -65.9 00. *	* ·0 - ·62.9 00. *	13.1 -65.9 00.	10.3 -64.2 00. *	01.6 -64.6 00. *	04.9 -65.4 00.	2.3 -66.2 00.	99.8 -67.0 00.	7.4 -67.8 00.	-0- 068-5	2.6 -66.2 00.	0-3 -66.3 00.	8.1 -67.1 00.	5.9 -68.0 00.	3.7 -68.9 00.	1.6 -69.4 00.	9.6 -69.8 00.	7.6 -70.2 00.	5.6 -69.9 00.	3.8 -67.1 00.	<u>.9 -67.2 00.</u>	0.1 -67.3 00.	8-4 -66-5 00-	6.7 -64.1 00.	1 -63.2 00. *

** AT LEAST GNE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION.

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont)

EOMETRIC LTITUDE SL FEET	PRESSURE MILLIBARS	TEMF AIR DEGREES	EMPERATURE DEWPOINT ES CENTIGRADE	RELATIVE HUMIDITY PERCENT	DENSITY GM/CUBIC METER	SPEED OF SOUND KNOTS	WIND DA' DIRECTION DEGREES(TN)	SPEED KNOTS	INDEX OF REFRACTION
•	G	•	0	** 0-	05.	64.	9	2	0000
0.0	62.0	3	o	** .0-	103.0	563.7	1.69	13.2	
•	Ö	•	•	** °0-	00	63.	9.	•	.00002
۰	6	-63.9	•	** °0-	8	63.	62.1	•	00002
		•	•	** °O-	ŝ	65.	48.	4	.0000
	•	-61.2	o	++ 00-	2	.99	•	•	00002
•	4	-61.0	•	** °0-	•	. 19	99.	a.	00002
•	G	-61.0	•	** °0-	7	67.	26.	•	002
	2	-	•	** *0	į,	67.	0	•	.00001
0.00089	0		°	** °O-	e m	. 19	ŝ		001
	9	-60.8	°	** • 0-	-	67.	, N	•	001
	8		•	** • D-	•	68.	4.	-	00001
•	~		°	** •0-	2.	•69	12.	5	001
	9	 	•	++ •0-	Š	70.	73.	15.2	0000
•	S		°	** · 0	8	71.	34.	4	0000
٥	4	-	•	** • 0-	1.	72.	50	-	.00001
	B	\$	•	** °0-	6	73.	62.	•	0000
•	2	-56.5	•	** · 0	7	73.	265.7		.00001
	-	9	ô	** •0-	9	72.	18.	•	00001
	9	\$	ċ	•	*	72.	ċ	•	.00001
	9	\$	•	** •0-	'n	72.	÷	8.4	0000
٥	œ	-	o	** 0-	-	72.	÷	•	0000
	~	2	•	** °0-	•	72.	•	•	.00001
0	9	2	ċ	** · 0-	.	72.	6	5.9	00001
0.0	3	9	ဝံ	** °0-	7	73.	ŝ	•	00001
•	4		ċ	** 0-	5	76.	6	7.6	0000
0.0	S	2	°	** °0-	ŝ	78°	•	7.4	.00001
•	ω	å	•	** • 0-	2	77.	4.		.00001
		-54.2	o	** •0-	-	5.925	32.9	•	1.000011
0.0	~	5	•	** · 0 -	•		•	5	0001

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. **#**

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont)

INDEX OF REFRACTION	1.000011	•00	0001	0001	0	000	000	000	1.000009	8	8	1.000008	.00000	1.000008	• 00000	00000	1.000007	0	000	8	00	0000	1.000006	000	0000	0	0000	00	1.000005
DATA SPEED KNOTS	20.5	0	6		-	•			•	9.1		11.5	•	15.0			•	•		16.5	•		. •				16.9		16.5
WIND DA DIRECTION DEGREES(TN)	62.4		2.	75.9	6	-	å	•	50	S	5.	85.2	5.	5	5	5.		5	4.	7	ò	ô	ŝ	ф	0	76.2	•	77.8	9.62
SPEED OF SOUND KNOTS	574.5	75.	76.	577.4	78.	78.	.61	80.	81.	81.	82.	82.	82.	82.	82.	82.	82.	83.	83.	œ	ω	∞	8	588.1	∞	588.1	588.1	588.1	588.1
ENSITY M/CUBIC METER	49.4	9	45.7	44.5	•	42.3	•	•			•	36.3			•	•	•	۰	•	29.8		•	7	27.1		5	25.3	•	24.2
ပ ပ																													
RELATIVE D HUMIDITY G PERCENT	***	** *0-	** • 0-	** 0-	** •0-	** •0-	+* •0-	** •0-	** °0-	** •0-	** •0-	** •0-	+* •0-	** •O-	** •0-	** *0-	+* •0-	+* •0-	+* •0-	** • 0-	** •0-	** • 0-	** •0-	++ •0-	** °0-	** •0-	** 0-	-C. **	**
E RELATIVE INT HUMIDITY RADE PERCENT	• •	0-	• 0-	0-	0-	-0-	-0-	0-	.0-	0-	.0-	0-	0-	0-	-0-	0-	-0-	-0-	0-	.0-	0-	0-	0-	0-	• 0-	-0-	• 0-	ာ ၁	* •0-
RATURE RELATIVE DEWPOINT HUMIDITY ENTIGRADE PERCENT	0-0-	54.4 00.	3.8 00.	53.3 00.	2.7 00.	2.1 00.	1.6 00.	1.0 00.	.5 0.	.9 0.	.5 00.	4 0 -0-	.3 00.	.3 C0.	.2 00.	.1 00.	0-0-0-0-6	• 0 - 0 - 6•	.0 - 0.	0- 0-	.0- 0.	.0- 0.	.00-	•0	•0- 0•	•0-	•0 -0•	.0	.1 00. #
TEMPERATURE RELATIVE AÎR DEWPOINT HUMIDITY EGREES CENTIGRADE PERCENT	55.5 00.	9.4 -54.4 00.	8.8 -53.8 00.	8.1 -53.3 00.	7.4 -52.7 00.	6.8 -52.1 00.	6.2 -51.6 00.	5.6 -51.0 00.	5.0 -50.5 00.	4.4 -49.9 00.	3.9 -49.5 00.	3.3 -49.4 00.	2.8 -49.3 00.	2.3 -49.3 00.	1.8 -49.2 00.	1.3 -49.1 00.	0-8 -49.0 00.	0.3 -48.9 00.	9.8 -48.3 00.	00- 9.446.6	9.0 -45.0 00.	8.5 -45.0 00.	8.1 -45.0 00.	7.7 -45.0 00.	7.3 -45.0 00.	6.9 -45.0 00.	6.6 -45.0 00.	6.2 -45.0 06.	5.8 -45.1 00. #

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *****

UPPER AIR DATA 3914309 WHITE SANDS SITE TABLE VII (Cont)

GEOMETRIC ALTITUDE	PRESSURE	TEM! AIR	EMPERATURE Dewpoint	RELATIVE HUMIDITY	NS I TY /CUBIC	SPEED OF SOUND	WIND IRECTION	DATA SPEED	INDEX
SL FEE	MILLIBARS	DEGREES	۸×	PERCENT	METER	KNOTS	DEGREES(TN)	KNOTS	REFRACTION
93500.0	15.5	-45.1	•	** •0-	23.6	588.1	œ	15.6	
94000.0	•	-45.1	•	+* •0-	3	588.1	•		.00000
_	. •	-45.1	ဝံ	+* ·0-	22.6	0	2	•	•
95000.0	14.5	-45.1	•	** •0-	•	588.0		11.5	1.000005
95500.0	•	-45.1	•	** *0-			4.		•
0.00096	13.8	-45.1	•	** 0-	21,1	588.0		9.5	•
96500.0	•	•	°	** •0	0		4	•	•
	13.2	-44.3	ဝ	+* ·D-	20.1		72.3	•	1.000004
97500.0	•		•0	** *0	9	290.0	ċ	9	٠
		-42.8	ö	** •0-	Q,	•	\$	•	.00000
	•		•	** · 0-	φ		9		.00000
		-41.3	•	+* •0-	18.1	•	•		1.000004
99500.0	•	-41.1	•	++ •0-	7	•	•		00000
.00000	•	•	•	** *0-	7		•	•	•
100500.0	-	-41.0	°	** *0-	•	593.2	6	14.5	•
01000.	-		•	** °0-	•		•	•	1.000004
101500.0		-41.0	•	++ •0-	•		•	•	•
02000	0	-41.0	•	++ 0-	۰		80.8	•	1.000004
102500.0			•	** °0			°	15.8	00000
03000.	0	•	•	++ •0-	•	593.4		•	•
03500.		6.05-	•	++ •0-		593.4		9	1.000003
104000.0		•	•	** •0-		593.5			•
C			•	** 0-	14.2	•			•
\mathbf{c}	•	•	•	-0- **	•				•
105500°C	0.6	-39.5	•	** · O-	13.5	•			.00000
106000.0		æ	•	** •0-	13,1	596.5			1.000003
0	8.7	-37.4	ဝံ	++ •0-	12.8	597.8			1.000003

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *

UPPER AIR DATA 3914310 WHITE SANDS SITE TABLE VIII

STATION ALTITUDE 3989.0 FEET MSL 23 MAY 66 2207 HRS MST ASCENSION NO. 374

	INDEX	REFRACTION		0025	0024	024	000	33	22	22	22	21	.00021	.00021	•00050	2	.00020	020	.00019	019	916	610	0018	0018	0018	.00018	0017	17	0017	0017	0	910
	ACDEF	KNOTS	0			•	11.6	'n	&	6	6	0	•	0	0	19.9	6	ċ	0	0	•	9.	0	0	0	1.]	•	2.	2.	3	4
	NIM	DEGREES(TN)	0	59.	40.	20.	301.6	82.	.69	67.	.99	64.	63.	62.	.09	57.	53.	49.	45.	41.	37.	32.	29.	27.	26.	24.	23.	22.	20.	16.	12.	.60
7	SPEED OF	KNOTS	669.7	70.	77.	75.	674.8	73。	72.	70.	• 69	67.	65°	64.	62.	60.	59°	57.	55.	54.	52.	50.	49.	47.	45°	43°	42.	40.	38°	36.	635.2	33°
	DENSITY	METER	031.	30.	91.	78.	964°5	51.	38.	26.	14.	32.	91°	80.	.69	858.0	* 6•	35.	24.	13.	03.	92.	82.	71.	61.	51.	40°	31.	20°	0,	00	90°
	RELATIVE	ERCENT	÷	0	7	-	16.4	ςů	•	Š	9	0	7.	~	ဆိ	19.2	0	2.	4.	rŲ.	7	6	-	4.	7°	0	Š	•	-	ŝ	င်	5°
	ERATURE	CENTIGRADE	•	9		•	-1,1	-2.5	-3.8	-4.5	۰	-5.8	9-9-	-7.3		•	-8.9	-9.2	-9.5		-10.4	-10.9	-11.2	-11.4		-12.0	2	-12.9		-13.4	-13.8	-14.3
	EMP	DEGREES	2	2	Φ	7	26.4	'n		3	-4	o	8	7	Ŋ	4.	'n.		ó	æ					•	9	9		ę	0.9-	•	8 8 -
	PRESSURE	MILLIBARS	76.	75	60.	45.	(L)	17.	03.	88	75.	61.	48	34.	22.	60	96	83.	71.	59	47.	35.	23.	12.	9	89.	78.	67.	56.	45.	350	525.0
	GMETR	ACITIONE MSL FEET	986	000	500°	000	500	.000	500°	000	500	000	8500°	0000	500	0000	0500.	000	1500.	2000.	2500.	3000.	3500.	000	4500.	5000.	5500°	60009	6500°	7000	7500.	

UPPER AIR DATA 3914310 WHITE SANDS SITE TABLE VIII (Cont)

INDEX OF REFRACTION	1-000161	00015	1.000154	0015	00014	00014	00014	00013	00013	0013	00013	.00012	.00012	.00012	.00012	.00012	00011	.00011	.00011	0011	00011	0100	0100	0100	000010	0100	6000	6000	60000	6000
SPEED KNOTS	75	, ,	27.4	ý	9	Š	ŷ	7	ċ	8	S.	Š	-	8	-	'n	•	Č	•	å	ċ	ċ	ċ	•	6	å	-			76.4
WIND DA DIRECTION DEGREES(TN)	4.40	06.	207.9	12.	19.	28.	36.	43.	47.	51.	55.	56	56.	57.	56.	55.	54.	53.	53.	53.	52.	52.	53.	53.	54 .	54 °	54.	54.	54.	53.
SPEED OF SOUND KNOTS	32	30,	628.8	27.	27.	25.	24°	23.	22.	20.	19.	18.	16.	15.	13.	12.	10.	.60	37.	35.	04.	32.	90.	98.	98.	. 16	96.	96	595.4	CD.
DENSITY GM/CUBIC METER	80	70.	661.0	50.	38.	28.	18.	08.	98.	88.	79.	•	60.	51.	43.	34.	25.	17.	.60	01.	494.1	86.	478.6	0	461.9	2.	4°	435.3	26.	6
RELATIVE HUMIDITY PERCENT		9	52.8	-	•	•		6	•	6	6	20.3	ö	-	7	2	5	ę	0	5	ó	'n	-	37.9	34.6	31.4	23°6**	•	0.6**	++ °0-
ERATURE DEWPOINT CENTIGRADE	•	18		9		3	4.	4	5	-36.5	-	-38.1	8	6	<u>:</u>	•	-42.1	•	-41.7	•	-41.7	•	3	-45.9	•	8	-	-57.6	6	
TEMPE AIR DEGREES C	-10.1	-	-12.6	•	ä	4	•	ġ	8	6	ċ	•	·	ä		Š	7.	8	6	.	2	*	ŝ	•	7	-	.	80	6.	o.
PRESSURE MILLIBARS	14.	04.	484.7	85.	75.	65°	56.	47.	38°	29.	20.	12.	03.	95.	87.	.62	71.	63.	56°	48.	410	340	260	19.	12.	05.	• 66	92.	86.	80.
OMETRIC TITUDE L FEET	500.	000	9500.0	.000	500°	900	1500.	2000°	2500.	3000.	3500.	4000	4500.	5000.	500.	000	500.	7000.	7500.	8000°	8500.	9000.	9500.	000	0200.	1000.	1500°	2000-	2500°	000

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *****

UPPER AIR DATA 3914310 WHITE SANDS SITE TABLE VIII (Cont)

STATION ALTITUDE 3989.0 FEET MSL 23 MAY 66 2207 HRS MST 374

ASCENSION NO.

Ξ	O FEET	ш
COORDIN	488,580	85,045
SITE	E 4	Z
MSTM		

INDEX OF REFRACTION	60000	6000	.00008	0008	.0000	•	.00008	• 0000		.0000	.0000	.0000	20000	.0000	.0000	1.000069	.00006	•0000	.0000	.0000	90000	90000	00000	.00005	.0000	.0000	.0000	1.000053	1,000052	1.000051
SPEED KNOTS	76.3	ę.	ô	40	ċ	4.	4°	4.	94.2	S.	3	ŝ	8	4.	-	88.4	Š.	•	.	0		٥	X		-	7	7	8	•	ċ
WIND DATA	53.	54.	56.	258.3	50.	52.	53.	63.	63。	63.	62.	62.	61.	61.	61.	261.3	60.	9	99	61.	62.	50,	99	69.	73.	76°	770	770	1	276.4
SPEED OF SOUND KNOTS	92.	91.	90°	90	68	587.9	86.	85.	83.	82.	80.	962	77。	76.	74.	573.5	72.	77	70.	69	69	9	0	. 69	68.	67°	660	65°	64°	Ô
DENSITY SGM/CUBIC METER	12.	04.	.96	388.1	80.	73.	999	60.	53.	47.	41.	35.	29.	23.	17.	311.1	04.	98•	92.	86.	62	72.	99	09	54.	•65	440	239.1	234.1	229.1
RELATIVE HUMIDITY PERCENT	+* *0-	** °0-	++ •0-	+* -0-	** °0-	** °0-	+* °0-	++ 0-	** °0-	** 0-	** °0-	** • 0-	+* •0-	** °0-	++ •0-	** °0-	** •0-	•	** • 0	•	•	•	•	** • 0-	** °0-	** 。0-	** °0-	-C. **	-0° **	** 0-
ERATURE DEWPOINT CENTIGRADE	°	°	°	•	•	°	o	°	•	ဝ		0	°	0	ċ	ċ	ဝ	o	•	°	•	°	°	ဝိ	0	ô	°		°	°
RATURE DEWPOINT ENTIGRAD	0	.5	3.0	3.4	۲.	•2	63	יני	9.	9.7	0 6.0	2.0	3.2	4.3	5.4	-56.2 0.	7.0	7.8	8.6	4.6	9.1	8 8	8.8	9.5	0.2	0.8	1.5	2,2	2,8 0	.5
TEMPERATURE AIR DEWPOINT EGREES CENTIGRAD	73.8 -41.8 0	67.7 -42.5 0	61.8 -43.0	55.9 -43.4	50.2 -44.1	44.5 -45.2	38.9 -46.3	33.4 -47.5	28.0 -48.6	22.8 -49.7 0.	17.7 -50.9 0.	12.7 -52.0	07.9 -53.2	03.1 -54.3	98.4 -55.4	7 -56.2	89.1 -57.0 0	84.6 -57.8 0	80.2 -58.6	76.0 -59.4	71.8 -59.1	67.7 -58.8	63.6 -58.8	59.7 -59.5 0	55.8 -60.2	52.1 -60.8 0	48.4 -61.5	4.8 -62.2 0	1.3 -62.8 0	9 -63.5 0

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. **#**

INDEX OF REFRACTION	1.000050	9000	0000	0000	9	0000	0000	0000	00000	0000	0000	0000	90	0003	0000	0000	0000	60000	0000	.00003	0003	.00003	.0000	.0000	.00002	.00002	.00002	.00002	0000	0
SPEED KNOTS		ò	_0	9.	-	'n	6	÷	6	6	ô	3	55.1	•	Š	1.	-	å	*	Ç		5	Š	3	œ.	10	Ð	•	0	8.4
WIND DA DIRECTION DEGREES(TN)	75.	74.	72.	70.	68.	65.	62.	59.	56.	S.	54.	54.	255.1	S S	56.	56.	57.	58.	59.	51.	55.	69°	3.	77.	84.	950	21.	\$2.	36.	N
SPEED OF SOUND KNOTS	2	62.	561.7	61.	.09	62°	63,	63.	63.	62°	61.	61,	560.4	59.	59.	59.	99	59.	58.	56.	55.	54.	53.	54.	56.	57.	58.	59.	61.	62.
DENSITY S GM/CUBIC METER	24.	19.	214.3	.60	040	Ò	92.	87.	83.	19.	75.	71.	168.0	64.	•09	56.	51.	48.	145.7	42.	6	36.	å	ċ	ŷ	å	8	Š	112.1	æ
_																														
ATIVE IDITY CENT	*	**	** •	**	**	**	* *	**	*	**	**	**	*	*	* *	** 。	*	*	* *	**	* *	*	* *	* *	*	**	*	* *	*	*
RELATI HUMIDI PERCEN	-0- **	-0° **	** *0-	+* °0-	+* °0-	** °0-	** °0	** • 0-	** •0-	** *0	++ °0-	** 0-	** °0	** •0-	•		** 0	** °0 -	** °0-		*	-0° **	** *0	*	•	** °0-	-0° **	** °0-	++ 00-	** °0 ··
FURE RELATI MPOINT HUMIDI FIGRADE PERCEN		•	•	•	•	•	•	•	•	•	•	•	** *0	-0	• 0	0-	0-		0-	0-	* 0	•	•	* °0-	°0-	0-	0-	0-	0-	•
RELATI NI HUMIDI ADE PERCEN	4.2	64.7 0.	5.0	5.4 0.	5.6 0.	4.5	3.5	.5	64.0 0.	64.5	5.0	5.5 0.	66.0	0- 0 9-9	7.1 00.	0 0-9	66.0 00	0.	7.8 00	8.7 00.	* °0 - °0 9•6	0.6 00	1.1	0.2 00. *	•2 6• -0•	8.3 00	7.3 00	.0	5.4 00	• 5
TEMPERATURE RELATI AIR DEWPOINT HUMIDI EGREES CENTIGRADE PERCEN	34.5 -64.2 0	31.3 -64.7 0.	8.0 -65.0 0.	24.9 -65.4 0.	21.8 -65.6 0.	18.8 -64.5 0.	5.9 -63.5 0.	13.1 -63.5 0.	0.364.0	07.6 -64.5 0.	04.9 -65.0 0.	02.4 -65.5 0.	8 -66.0 0.	7.4 -66.6 00	5.0 -67.1 00.	2.7 -66.6 00	0.4 -66.0 00	8.1 -66.9 00	5.9 -67.8 00	3.8 -68.7 00.	1.7 -69.6 00. *	9.6 -70.6 00	7.6 -71.1 0.	5.7 -70.2 00. *	3.8 -69.2 C0.	2.0 -68.3 00	0.2 -67.3 00	8.5 -66.4 00	.8 -65.4 00	5.2 -64.5 0

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *****

UPPER AIR DATA 3914310 WHITE SANDS SITE TABLE VIII (Cont)

	REFRACTION	.0000	0005	.00002	0002	1.000021	0002	0002	0000	00000	00.	.0000	0000	.00001	0000	.0000	0	•00001	000	000	0000	~	0001	1000	0001	0001	00000	0001	1.000012	1.000012	001
TA SPEED	KNOTS	0	0	9	•	12.8	•	ທໍ	2°		٥	٥	0	11,07	•	2	•	ဝိ		0	0	ô.	•	9.4	9	٠.		•	0	0	•
WIND IRECTIO	DEGREES(TN)	11.	297.0	12。	28.		0	ů.	2	90•	å	-	ထိ	152.6	٦,	ę,	.	/•	Š	(L)	ŝ	101.6	ŷ,		ŝ	0	,	70°1	0		ဝိ
SPEED OF SOUND	KNOTS	•	65°	• 99	999	566.8	67.	57.	68°	68°	68	.69	569.7	570.2	70.	571.0	71.	71.	72.	72°	73.	573.0	72°	72.	720	72.	~	720	-	72	~
DENSITY S	ш	05.	102.6	6	7	7.46	2.	•	7 .	0	3	•	6	77.2	Š	•	•	6	•	• 9	4.	3		•	ထိ	7	6،	54.7		52.1	0
- 0																															
ATIVE	CEN	** °0-	-C° **	++ 0-	** ·0-	** *0-	-0° **	** °0-	** •0-	C° **	** °0-	** 0-	-0° **	-0. **	-0. ##	** •0-	-0- **	** •0-	++ 0-	** *0-	** *0	-0° **	** °0-	** •0-	** *0-	** 0-	+* °0-	-0° **	-0° **	** °0-	** °0-
ERATURE RELATIVE DEWPGINT HUMIDITY	NTIGRADE PERCEN	i	* °0-	.0-	0	-0-	0-	-0-	•0-	o O	0-	0-	٥	•	-0-	-0-	.0-	0-	0-	0	•0-	•0-	٠		•	•	•	.0-	0-	0-	** 00- 00
RATURE RELATIVE DEWPCINI HUMIDITY	ES CENTIGRADE PERCEN	.5	62.6 OC. *	61.9 00.	.0 -0.	1.3 00.	•0- 0 6•	0-	0.3 00.	00 00	0- 0- 2-6	.4 00.	.0 0.	ဗ	.4 00.	.1 00.	.0 -0-	.5 00.	.2 00.	.00-	.5 00.	°9- °0 9°	.0 0.	.0 0.	.0	•0 6.	6.9	7.0 00.	7.1 00.	6.8 00.	•
EMPERATURE RELATIVE DEWPGINI HUMIDITY	EGREES CENTIGRADE PERCEN	3.5 -63.5 0.	2.0 -62.6 00. *	0.5 -61.9 00.	9.0 -61.6 00.	7.6 -61.3 00.	6.2 -60.9 00.	-0- 0 9.09 -0.4	3.6 -60.3 00.	2.3 -60.0 00.	1.0 -59.7 00.	9.8 -59.4 00.	8.6 -59.0 0.	7.5 -58.7 0.	6.3 -58.4 00.	5.2 -58.1 00.	4.2 -57.8 00.	3.1 -57.5 00.	2.1 -57.2 00.	1.1 -56.8 00.	0.1 -56.5 00.	9.1 -56.6 00.	8.2 -56.6 0.	7.3 -56.7 0.	6.4 -56.8 0.	5.6 -56.9 0.	4.7 -56.9 0.	3,9 -57.0 00.	3.1 -57.1 00.	2.4 -56.8 00.	56.5 0.

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION. *****

UPPER AIR CATA 3914310 WHITE SANDS SITE TABLE VIII (Cont)

INDEX OF REFRACTION	80	10000	00	0000	0001	_	00000		00000				\sim	\sim	1.000008	$\overline{}$	~	1.000007	_	~		\sim	8	1.000006	00000	0000	0000	1.000006	0000
SPEED KNOTS	16.9	•	12.8		•	•	•		•	•	15.2		3	•	-	-	٠	-			14.9	å	18.9	0	17.2	•	9	16.2	•
WIND DA DIRECTION DEGREES(TN)	75.9	• D Q	• • • •	æ	78.1	&		83.4	9	•		•	6	01.	2	02.	02.	9	0	86.9	*	0	8*06	6	88.3	æ	8	88.2	4 °
SPEED OF SOUND KNOTS	573.5	.07	740	75.	75.	75.	76.	76.	17.	77.	77.	78.	78.	.61	.61	.61	80.	80.	81.	81.	81.	82.	82.	83.	83°	83°	84.	584.5	84.
DENSITY GM/CUBIC METER	9.64	, r		•	43.9	2	-	ဝံ	9.	8	7	•	•9	5.	4.	ë	å	-	÷	30.3	6	å	8	7.	•	•	5	4	4.
RELATIVE HUMIDITY PERCENT	•	• • • • • • • • • • • • • • • • • • • •		** 0-	-0. **	** *0-	** °0-	** •0-	** ·0-	** *0-	** °O-	** • 0	-0. **	** *0-	++ •0-	** °0-	** ·0-	** °0-	-0° **	** ·0-	++ •0-	** •0-	** °0-	-0° **	** °0	** °0-	** °0 ·	++ 0-	** 0-
E RELATIV INI HUMIDIT RADE PERCENT	•	0 0	0	0-	•00-	0-	•0-	0-	•0-	•0-	0-	0-	0-	•0-	-0-	.0-	-0-	0-	°°°	* •0-	* • 0-	-0-	• 0-	-0-	0	°0-	0	0-	•
RATURE RELATIV DEWPOINT HUMIDIT ENTIGRADE PERCENT	56.2 00.	000	יים פיים פיים פיים פיים פיים פיים פיים	5.0	4.7 00.	4.4	4.1 00.	3.8 00.	3.5 00.	3.2 00.	2.9 00.	2.6 00.	2.3 00.	2.0 00.	1.7 00.	1.4 00.	1.1 00.	0-8 0-	0.5 00.	* •0-	* ·0 - 6 · 6	• 0 - 0 9 •	•3 0• -0°	.0 0.	00.	0.0	•1 00	7.8 00	7.5 0.
TEMPERATURE RELATIV AIR DEWPOINT HUMIDIT EGREES CENTIGRADE PERCENT	56.2 00.	01 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		8.1 -55.0 00.	7.5 -54.7 00.	6.9 -54.4 0.	6.2 -54.1 00.	5.6 -53.8 00.	5.1 -53.5 00.	4.5 -53.2 00.	3.9 -52.9 00.	3.4 -52.6 00.	2.8 -52.3 00.	2.3 -52.0 00.	1.8 -51.7 00.	1,3 -51,4 00.	0.8 -51.1 00.	0.3 -50.8 00.	9.9 -50.5 00.	9.4 -50.2 00. *	* ·0- 0 6 6 -6 - 0 · 6	8.5 -49.6 00.	8.1 -49.3 00.	7.7 -49.0 00.	7.3 -48.7 00.	6.9 -48.4 00.	6.5 -48.1 00.	6.1 -47.8 00	5.7 -47.5 0.

** AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION.

UPPER AIR DATA 3914310 WHITE SANDS SITE TABLE VIII (Cont)

INDEX OF	REFRACTION	1.000005	1.000005	1.000005	1.000005	1.000005	1.000005	1.000005	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000004	1.000003
TA SPEED	KNOTS	17,3	18.4	20.4	22.4	23.0	22.6	22.3	21,3	20°5	19.1	17.1	15.0	12.8		-				
WIND DATA	DEGREES(TN)	80.1	77.5	77.5	77.5	77.5	77.5	77.5	77.5	77.5	77.5	77.5	٥	77.5				-		
SPEED OF SOUND	KNOTS	585.3	585.7	586.1	586.5	586.9	587.3	587.7	588.1	588.4	588.7	589.0	589.3	589.7	590.0	590.3	590.6	6.065	591.3	591.6
DENSITY S	METER	23.7	23.1	22.6	22.0	21.5	21.0	20°2	20.0	19.5	19.0	18.6	18.2	17.7	17.3	16.9	16.5	16.1	15.8	15.4
1 V E	<u></u>	#	*	*	*	*	*	*	*	*	*	*	# #	*	*	*	*	*	*	*
RELATIVE HUMIDITY	PERCENT	* °0-		0-							-0-	-0-	°0-						° 0-	, 0-
N N	ш	* °0-		00.	.0-				°0-	°°		00°			-0-	°0-	.0-	°0-	۰	
	ES CENTIGRADE	-47.2 C0. *	°0-	•	.0-	°0-	0- 00	•0-	°0-	°°				000	-0-	°0-	.0-	°°°	-0-	
EMPERATURE DEWPCINT	CENTIGRADE	.4 -47.2 0.	0 -0.	.7 -46.6 0.	00-	0 0 0	.7 -45.7 00.	0- 00	•1 -45.1 0° -0°	8 00.	.5 -44.6 0.	3 0°	.9 -44.1 0.	8 0.	00-	.2 -43.3 00.	-43.1 0° -0°	.8 0.	0 0 -0°	2.3 00.

AT LEAST ONE ASSUMED RELATIVE HUMIDITY VALUE WAS USED IN THE INTERPOLATION.

Action				IMPACT	DISPLACEMENT		IN MILES	S DUE TO	CINIM C		THEOR	THEO RETICAL
TELLET	RELLASE, TLME (MST)		143- 1000	FΤ	4000- 20000	D FT	20000- 100000	- FT	TOTAL	AL	IMFACT IN MILES FROM LAUNCHER	IMFACT IN ILES FROM LAUNCHER
RAWIN	RAWINSONDE	PIBAL	N-S	E-W	N-S	E-W	N-S	E-W	N-S	E-W	N-S	E-W
R ₁ 1630	в 1630	P 1907	12.5N	29.7W	7.38	18,0W	0,98	20. LW	h.38	WI.89	54.2N	20.7W
R2 1905	R 1630	P 1937	14.3N	29.5W	6.2S	19.9W	0.98	20. LW	7.2N	M8.69	57.1N	22. LW
R2 1905	R 1630	P 2007	13.0N	30.8W	6.25	19.9W	0,98	20. ltw	5.9N	71.1W	55.8N	23.7W
R2 1905	в 1630	P 2027	30.0N	24.7W	6.25	19.9W	0.98	20. LW	22.9N	65.0W	72.8N	17.6W
R2 1905	R 1630	Р 2047	27.2N	25.9W	6.23	19.9W	0,95	20. LW	20.1N	66.2W	70.0N	18,8W
R2 1905	R ₃ 1905	P 2107	27.1N	19.9W	6.25	19.9W	4.38	17.9W	16.6N	57.7W	66.5N	10.3W
R2 1905	R ₃ 1905	P 2122	22.9N	15.5W	6.28	19.9W	4.38	17.9W	12,4N	53.3W	62.3N	5.9W
R2 2110	R3 1905	Р 2140	19.1N	15.0W	8,95	15.8W	4.38	17.9W	5.9N	48.7W	55.8N	1.3W
R2 2110	R3 1905	Р 2147	19.3N	MI.91	8,95	15.8W	4.38	17.9W	NI.9	49.8M	% on 26.0N	2.14W
R2 2110	R ₃ 1905	P 2157	14.3N	MI.91	8,98	15.8W	4,38	17.9W	1.1N	49.8W	51, ON	2. Ltw
*R1 2207	*R 2207	*P 2208	9.2N	15.7W	10,53	15.4W	5.23	20.3W	6,53	W1.12	43.4N	4.0W

2207 MST 23 MAY 1966

TIME: DATE:

IMPACT PREDICTION DATA AEROBEE NASA μ .51 UG

TABLE IX.

* = Post-Shoot Data
P = Double Theodolite Winds (143-4,000 FT)
R = Rawinsonde Winds (Above 20,000 FT)
R₁= Rawinsonde Winds (4,000-20,000 FT)
R₂= Rawin Winds (4,000-20,000 FT)
R₃= Rawin Winds (Above 20,000 FT)

JACK SETTINGS	West leg	28	inches	PREDICTED IMPA
FOR LATINCHER B	East leg	æ	inches	LAUNCHER
TATINGHER	Tilt	3.97	degrees	PREDICTED
SETTING	Azimuth	046.7	degrees	FROM LAUNCHER
E	North	2.73	2.73 degrees	RECOMMENDATION
COMPONENTS	East	2,89	2,89 degrees	confidence of range, based u
NO WIND IMPACT	North	49.9 miles	miles	
FROM LAUNCHER	E as t	47.4 miles	miles	23 May 1966/21

PREDICTED IMPACT	North	55.0	55.0 miles
FROM LAUNCHER	West	2.0	2.0 miles
PREDICTED	Azimuth	050	degrees
BOOSTER IMPACT FROM LAUNCHER	Distance	1,500	feet
RECOMMENDATION - Fire, with 90% confidence of impacting on range, based upon: wind correction of 19 1	Fire, with acting on : of bility	90% hy miles 14 miles	
23 May 1966/2153 MST	MST		

TABLE X. ACTUAL AND PREDICTED LAUNCH DATA AEROBEE NASA 4.51 UG

RADAR IMPACT	North	24.1	miles
FROM LAUNCHER	West	6.9	miles
ACTUAL BOOSTER	Azimuth	N/A	degrees
IMPACT FROM LAUNCHER	Distance	N/A	feet

NOTE: The peak altitude of the rocket was only 87 miles. Therefore, the rocket impacted short of the prediction.

TABLE XI. IMPACT DATA
AEROBEE NASA 4.51 UG

Security Classification

DOCUMENT CONTROL DATA - R&D (Security classification of title, body of shetrect and indexing annotation must be entered when the overall report is classified)							
1. ORIGINATING ACTIVITY (Corporate author)			SECURITY CLASSIFICATION				
U. S. Army Electronics Command		UNCLASSIFIED					
Fort Monmouth, New Jersey		2 b. GROUP					
3. REPORT TITLE	<u></u>						
METEOROLOGICAL DATA REPORT, AEROBEE NA	SA 4.51 UG						
4. DESCRIPTIVE NOTES (Type of report and inclusive dates)							
5. AUTHOR(5) (Lest name, first name, initial)							
Dunaway, Gordon L.							
6. REPORT DATE	74. TOTAL NO. OF PAGES		76. NO. OF REFS				
June 1966	214		2				
BA. CONTRACT OR GRANT NO.	Sa. ORIGINATOR'S REPORT NUMBER(S)						
b. PROJECT NO.	DR-36						
°DA Task IV650212A127-02	9b. OTHER REPORT NO(S) (Any other numbers that may be easigned this report)						
d.							
10. AVAILABILITY/LIMITATION NOTICES	,						
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11. SUPPLEMENTARY NOTES	12. SPONSORING MILITARY ACTIVITY						
ı	U. S. Army Electronics Command Atmospheric Sciences Laboratory White Sands Missile Range. New Mexico						
13. ABSTRACT			\ <u></u>				

Meteorological data gathered for the launching of Aerobee NASA 4.51 UG are presented for the National Aeronautics and Space Administration, Princeton University and for ballistic studies. The data appear, along with calculated ballistic data, in tabular form.

14 KEY WORDS	LINK A		LINK B		LINK C		
	ROLE	WT	ROLE	WT	ROLE	WT	
1. 2. 3.	Ballistics Meteorology Wind						
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